

Algorithms - Spring '25

Strongly & weakly
connected comps.
Intro to MST



Recap

- No class next week -
happy break!

- HW & readings for after
break are posted

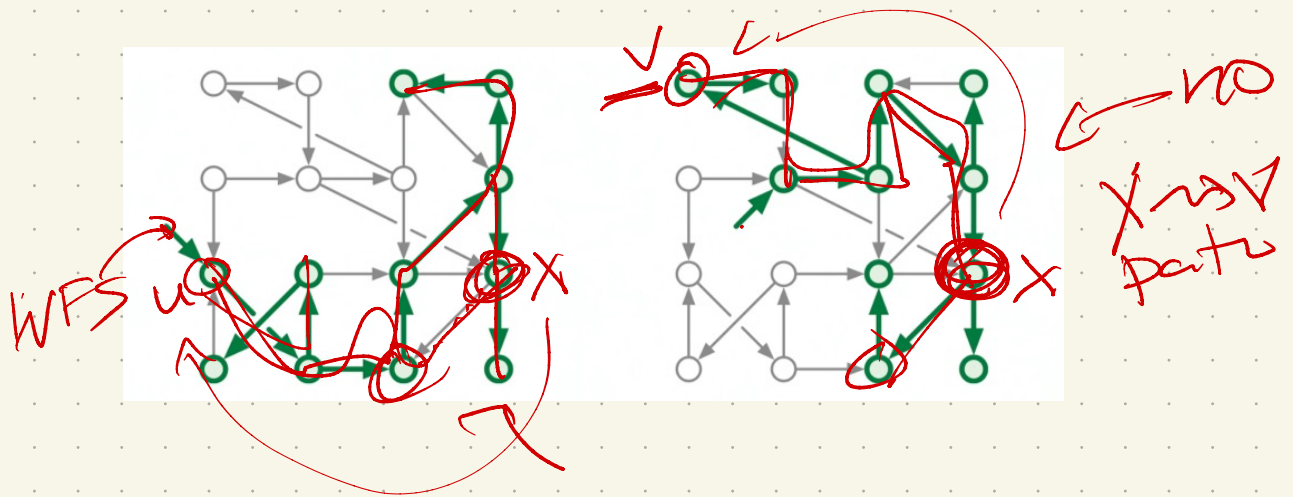
- Instructor feedback form
should be posted
(check email)

- Tuesday after break
↳ out of town, no
office hours
↳ makeup on Wed/Thurs

Strong connectivity

In an undirected graph,
if $u \rightsquigarrow v$, then $v \rightsquigarrow u$.

Not true in directed case!



So 2 notions:

weak connectivity:

u, v are weakly connected if
either $u \rightsquigarrow v$ or $v \rightsquigarrow u$

Strong connectivity:

both $u \rightsquigarrow v$ and $v \rightsquigarrow u$

related: SCCs strongly conn
comps.

Can actually order the strongly connected pieces of a graph:

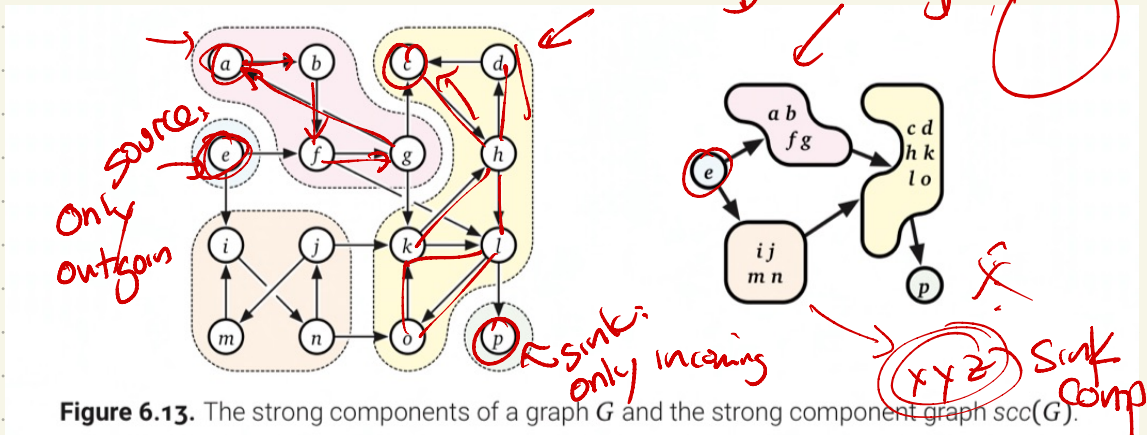
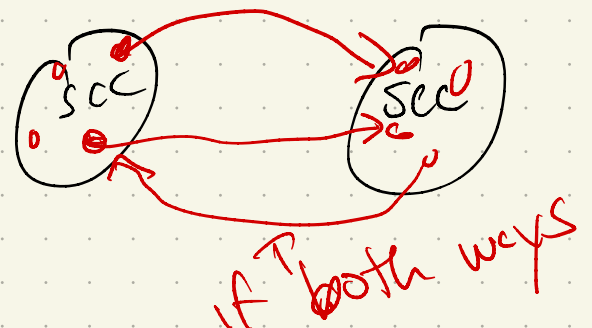


Figure 6.13. The strong components of a graph G and the strong component graph $scc(G)$.

How?

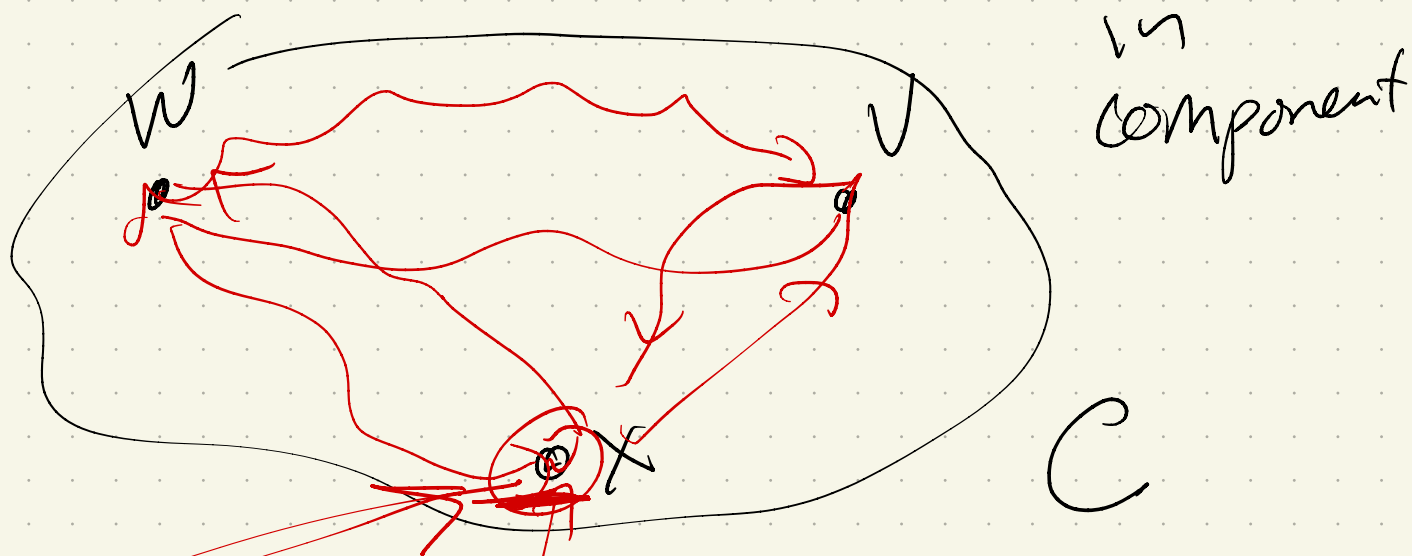
- Well, each component either isn't connected, or only has 1-way edges. Why?



More formally:

Every strong CC must have at least one vertex with no parent.
(or parent outside comp)

Proof: Consider two vertices



Let x be first vertex in clock-order in sec :



Possible to compute SCCs
in $O(V+E)$ time. ←

Need good sinks!

DFS (rev(G))

↳ find sinks

Then, reverse back to
G & run DFS from
them.

(See book for details)

Next module:

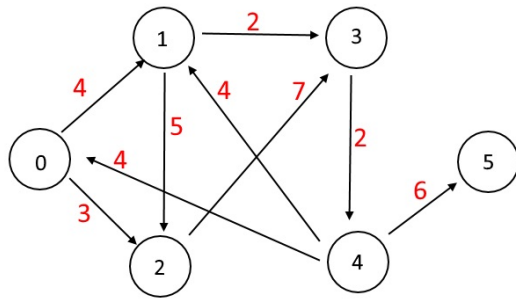
Minimum Spanning
trees

→ shortest paths.

Both are on weighted

graphs - so $G = (V, E)$,
plus $w: E \rightarrow \mathbb{R}$ (or \mathbb{R}^+)

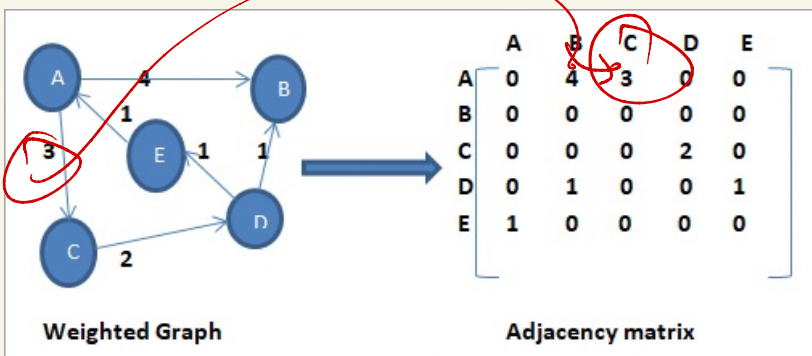
picture:



Weighted Graph

vertex 0
 $[1] = 4$
↓
 $[2] = 3$

↑
weight
of
edge



Minimum Spanning Trees

Goal: Given a weighted ^{undirected} Graph G ,
 $w: E \rightarrow \mathbb{R}^+$ the weight function,
find a spanning tree T of G
that minimizes:

$$w(T) = \sum_{e \in T} w(e)$$

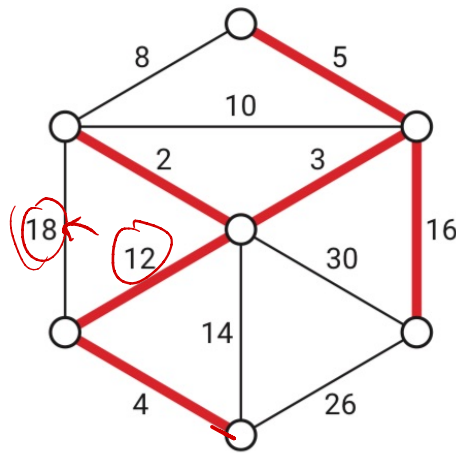


Figure 7.1. A weighted graph and its minimum spanning tree.

Motivation:

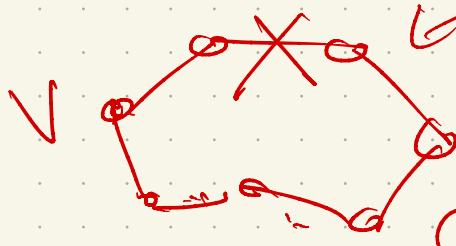
Connectivity:
tree is minimally connected
subgraph.

First:

Does it have to be a tree?

Yes, Why?

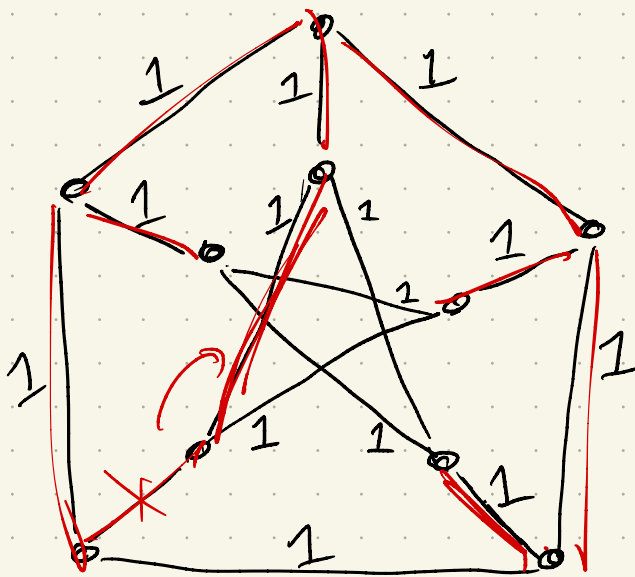
think contraction: if not: cycle
sum of all edges
if all possible
can be deleted



Second:

These are obviously not unique!

Ex:



tree?

any subtree works

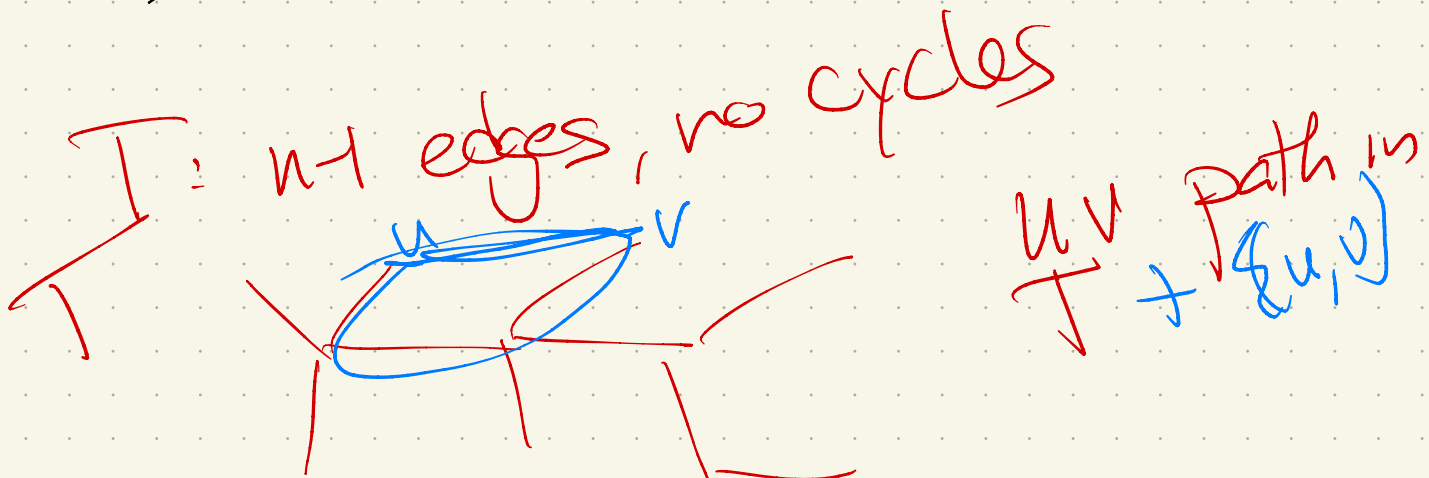
Things will be cleaner if we have unique trees. So:

Lemma: Assuming all edge weights are distinct then MST is unique.

Pf: By contradiction:

Suppose T & T' are both MSTs, with $T \neq T'$

- $T \cup T'$ contains a cycle. T' has at least one edge not in T .
 - That cycle must have 2 edges of equal weight.
- \Rightarrow Contradiction!



Now, what if weights aren't unique?

Just need a way to consistently break ties.

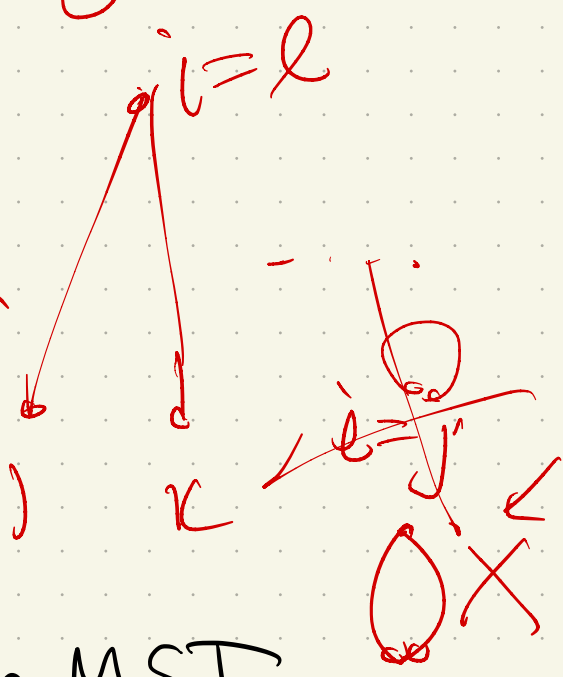
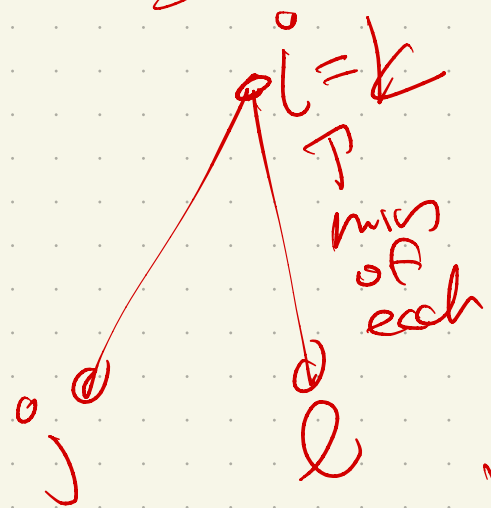
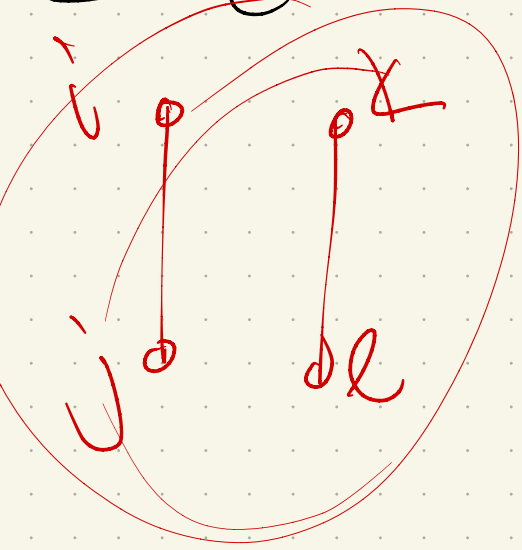
if min ind of vertex is smaller return that edge

s u i 8

SHORTEREDGE(i, j, k, l)	
if $w(i, j) < w(k, l)$	then return (i, j)
if $w(i, j) > w(k, l)$	then return (k, l)
if $\min(i, j) < \min(k, l)$	then return (i, j)
if $\min(i, j) > \min(k, l)$	then return (k, l)
if $\max(i, j) < \max(k, l)$	then return (i, j)
$\langle\langle$ if $\max(i, j) > \max(k, l)$ $\rangle\rangle$	return (k, l)

not tied

cases! we know edges have same weight.



So, takeaway:
Can assume unique MST.

Next: an algorithm.

The magic truth of MSTs:

You can be SUPER greedy.

Almost any natural idea
will work!

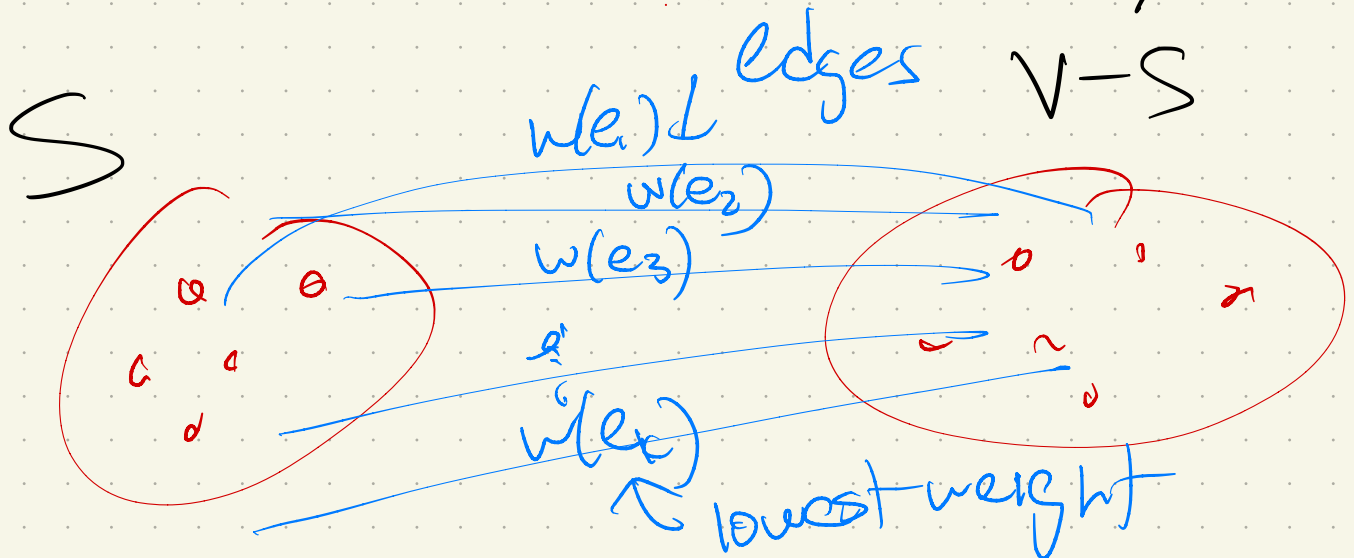
This is highly unusual, &
there's a reason for it:

these are a (rare) example
of something called a
matroid

(Way beyond this class...)

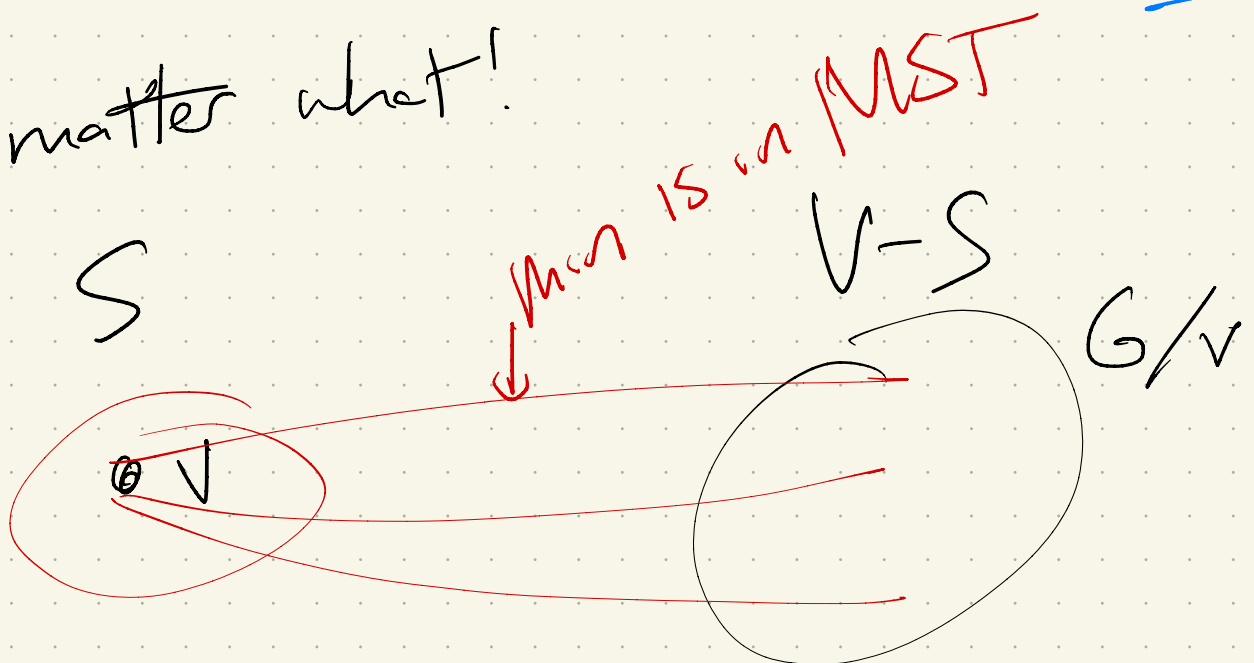
Key property:

Consider breaking G into two sets: S and $V \setminus S$

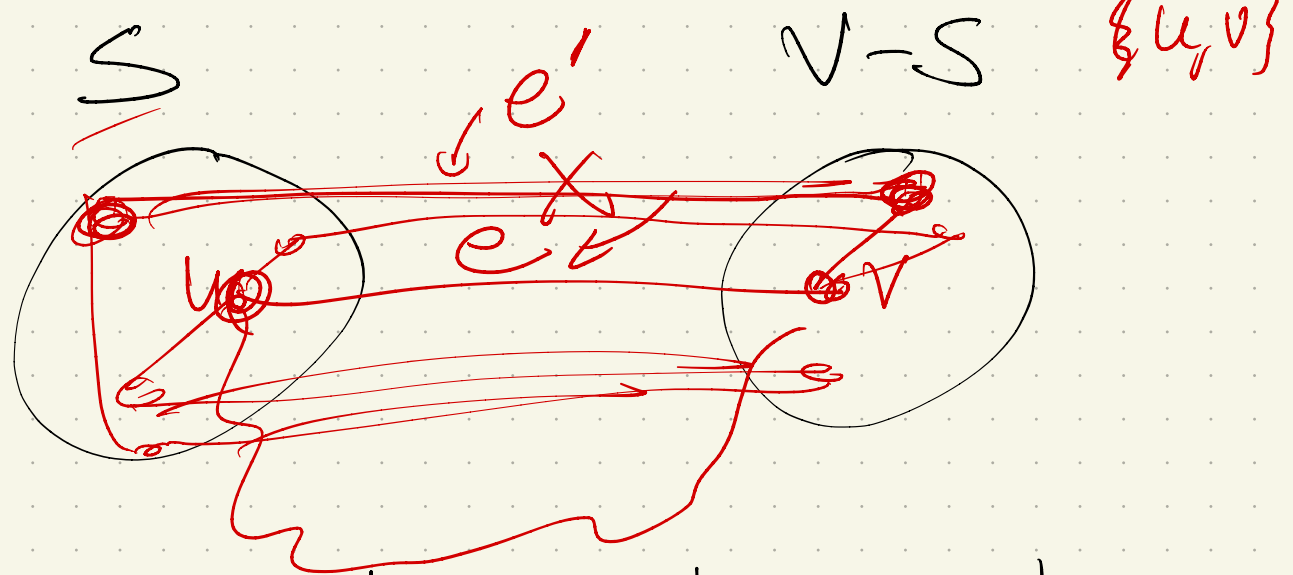


The MST will always contain the lowest edge connecting the two sides.

No matter what!



Proof: consider minimum edge e



Suppose MST does not contain e .

\Rightarrow MST must have some $u-v$ path not including $e \rightarrow$ call this p
 $p + e$ is a cycle.

for any $S' \subset S$ & $V-S$ with $u \in S'$ and $v \in V-S$, p must use some edge from S' to $V-S$.
Consider those edges \rightarrow all larger than e .

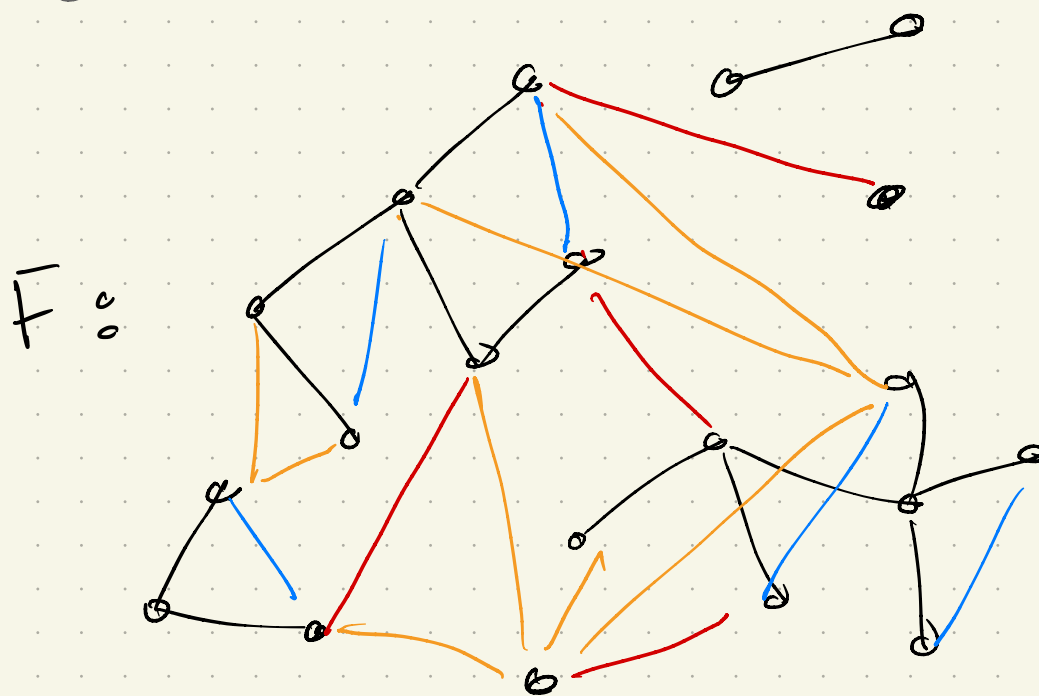
Generic Algorithm:

Build a forest: an acyclic subgraph.

Dfn: An edge is useless if it connects 2 endpoints in same component of F .

also edges that are useless.

An edge is safe if it is minimum edge from some component of F to another.



So idea:

Add safe edges
until you get a tree

If everything isn't connected,
must have some safe
edge.

Why?

Add it & recurse.

We'll see 3 ways:

① Find all safe edges.
Add them + recurse.

② Keep a single connected component

At each iteration, add
1 safe edge.

③ Sort edges + loop
through them.

If edge is safe,
add it.

First one: (1926-ish)

BORŮVKA: Add **ALL** the safe edges and recurse.

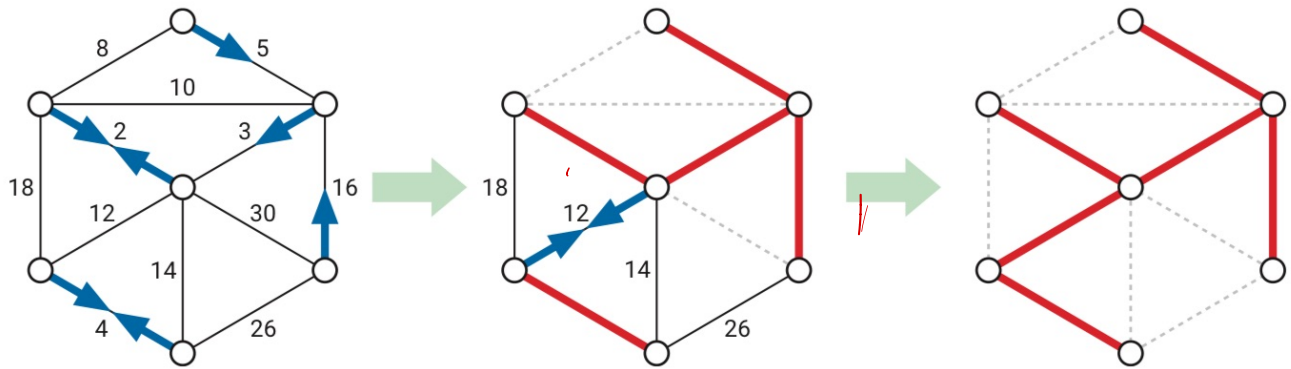


Figure 7.3. Borůvka's algorithm run on the example graph. Thick red edges are in F ; dashed edges are useless. Arrows point along each component's safe edge. The algorithm ends after just two iterations.

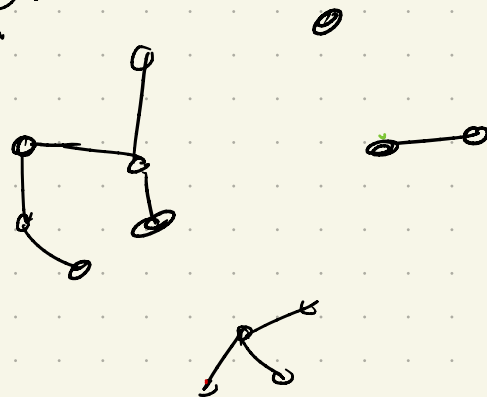
So we need to:

While more than 1 component:

- Track components
- Find all safe edges
- Add them

More formally:

Graph



BORŮVKA(V, E):

$F = (V, \emptyset)$

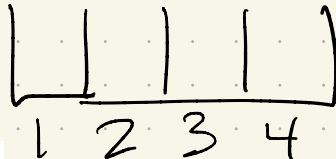
$count \leftarrow \text{COUNTANDLABEL}(F)$

while $count > 1$

 - $\text{ADDALLSAFEEDGES}(E, F, count)$

$count \leftarrow \text{COUNTANDLABEL}(F)$

return F

Safe: 

ADDALLSAFEEDGES(E, F, count):

for $i \leftarrow 1$ to $count$

$safe[i] \leftarrow \text{NULL}$

for each edge $uv \in E$

 if $comp(u) \neq comp(v)$

 if $safe[comp(u)] = \text{NULL}$ or $w(uv) < w(safe[comp(u)])$

$safe[comp(u)] \leftarrow uv$

 if $safe[comp(v)] = \text{NULL}$ or $w(uv) < w(safe[comp(v)])$

$safe[comp(v)] \leftarrow uv$

for $i \leftarrow 1$ to $count$

 add $safe[i]$ to F

Uses WFS-variant from Ch 5:

COUNTANDLABEL(G):

$count \leftarrow 0$

for all vertices v

 unmark v

for all vertices v

 if v is unmarked

$count \leftarrow count + 1$

$\text{LABELONE}(v, count)$

return $count$

«Label one component»

LABELONE(v, count):

while the bag is not empty

 take v from the bag

 if v is unmarked

 mark v

$comp(v) \leftarrow count$

 for each edge vw

 put w into the bag

Correctness:

- MST must have any safe edge
- We keep computing safe edges & adding
- Stop when # connected components = 1

⇒ Have the MST!

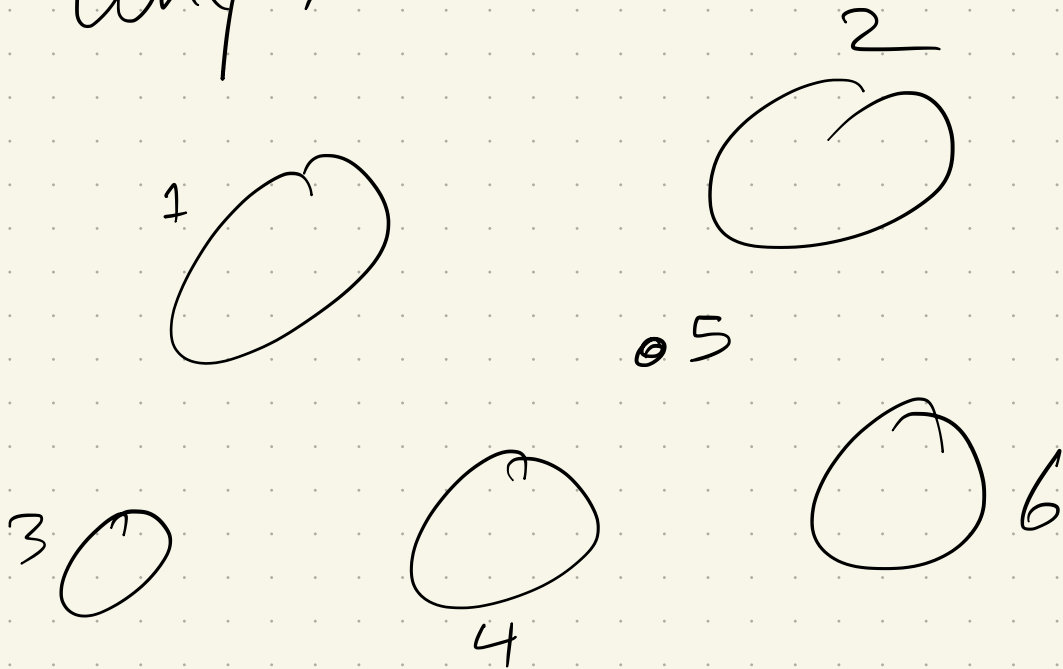
Run time:

A bit trickier!

Depends on how many safe edges we get.

Claim: There are at least $\frac{\# \text{components}}{2}$ safe edges each time.

Why?



So: runtime:

ADDALLSAFEEDGES($E, F, count$):

for $i \leftarrow 1$ to $count$

$safe[i] \leftarrow \text{NULL}$

for each edge $uv \in E$

 if $comp(u) \neq comp(v)$

 if $safe[comp(u)] = \text{NULL}$ or $w(uv) < w(safe[comp(u)])$

$safe[comp(u)] \leftarrow uv$

 if $safe[comp(v)] = \text{NULL}$ or $w(uv) < w(safe[comp(v)])$

$safe[comp(v)] \leftarrow uv$

for $i \leftarrow 1$ to $count$

 add $safe[i]$ to F

↑ Looks at each vertex & edge
in worst case:

BORŮVKA(V, E):

$F = (V, \emptyset)$

$count \leftarrow \text{COUNTANDLABEL}(F)$

 while $count > 1$

 ADDALLSAFEEDGES($E, F, count$)

$count \leftarrow \text{COUNTANDLABEL}(F)$

 return F

BFS/DFS
on tree:

How many
iterations?

So: runtime.

ADDALLSAFEEDGES($E, F, count$):

for $i \leftarrow 1$ to $count$

$safe[i] \leftarrow \text{NULL}$

for each edge $uv \in E$

 if $comp(u) \neq comp(v)$

 if $safe[comp(u)] = \text{NULL}$ or $w(uv) < w(safe[comp(u)])$

$safe[comp(u)] \leftarrow uv$

 if $safe[comp(v)] = \text{NULL}$ or $w(uv) < w(safe[comp(v)])$

$safe[comp(v)] \leftarrow uv$

for $i \leftarrow 1$ to $count$

 add $safe[i]$ to F

↑ Looks at each vertex & edge
in worst case:

BORŮVKA(V, E):

$F = (V, \emptyset)$

$count \leftarrow \text{COUNTANDLABEL}(F)$

while $count > 1$

$\text{ADDALLSAFEEDGES}(E, F, count)$

$count \leftarrow \text{COUNTANDLABEL}(F)$

return F

→ BFS/DFS
on tree

↳ How many
iterations?