

Algorithms - Spring '25

DFS, BFS,
& variants



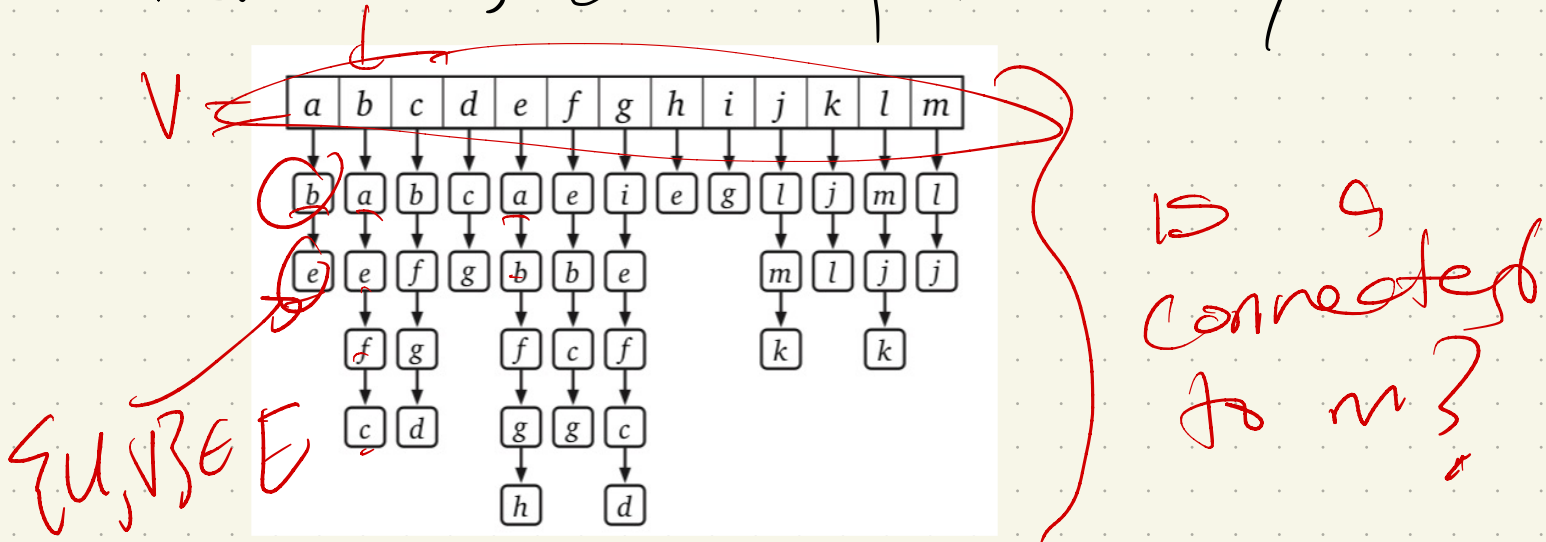
Recap

- Oral grading - starts today
(No office hours tomorrow)
- Exam next Tuesday
 - review session Monday
 - practice exam posted
- Reading due Friday, then
next Wednesday

Graph Searching

How can we tell if 2 vertices are connected?

Remember, the computer only has:



Bigger question: can we tell if all the vertices are in a single connected component?

Possibly you saw depth first search (DFS) and breadth first search (BFS) in data structures:

WHATEVERFIRSTSEARCH(s):

put s into the bag

while the bag is not empty

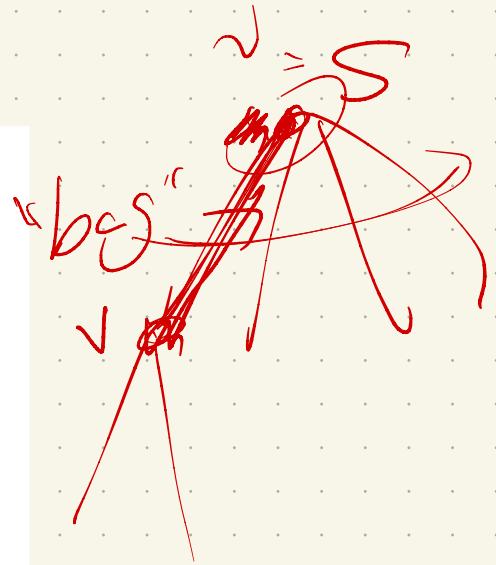
take v from the bag

if v is unmarked

mark v

for each edge vw

put w into the bag



These are essentially just search strategies:

How can we decide if u + v are connected?

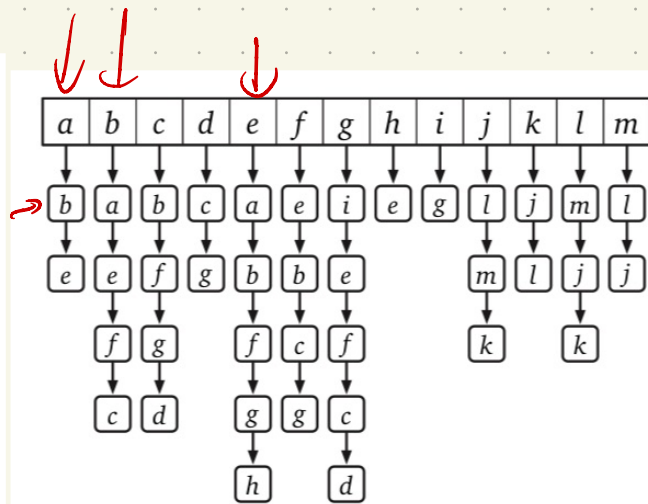
Q: what "bag"?

lots of data structures!

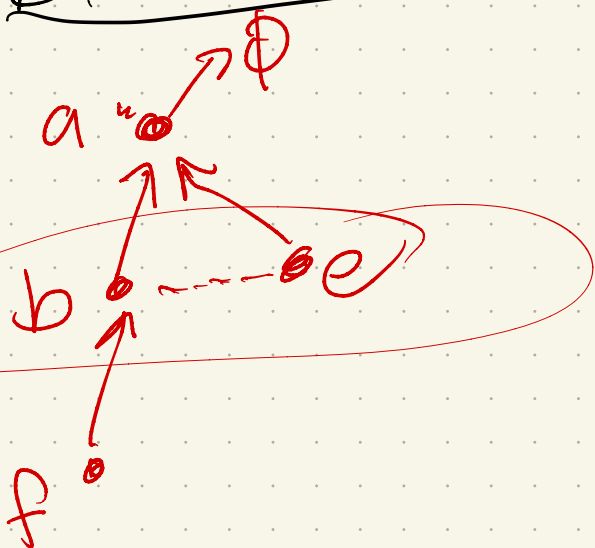
Can use this to build a spanning tree:

WHATEVERFIRSTSEARCH(s):

put (\emptyset, s) in bag *queue*
 while the bag is not empty
 take (p, v) from the bag (*)
 if v is unmarked
 mark v
 parent(v) ← p
 for each edge vw (†)
 put (v, w) into the bag (**)



BFS tree:

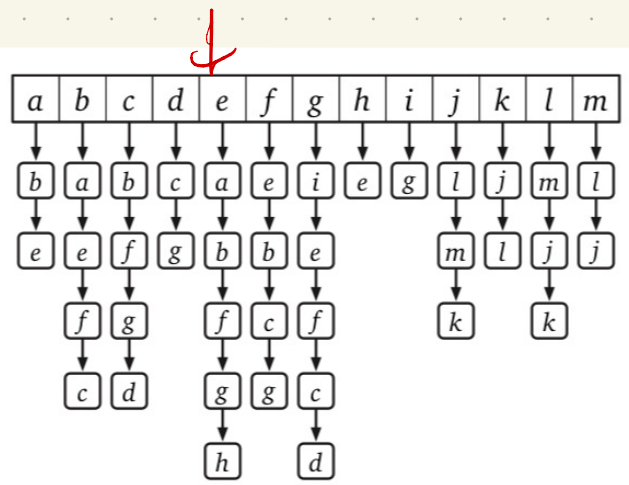


queue: ∅(∅, s) : O(1) per operation

front
~~(∅, a)~~, ~~(a, b)~~ back
 remove → ~~(a, e)~~, ~~(e, f)~~ add
 → ~~(b, a)~~, ~~(b, e)~~
 (b, f), (∅, c),
 (e, a), (e, b), (e, f) →
 es bns
 (f, v) = ~~(∅, a)~~ → (b, e)
 (c, b) (b, f)
 (a, e)
 (∅, e)

WHATEVERFIRSTSEARCH(s):

put (\emptyset, s) in bag
 while the bag is not empty
 take (p, v) from the bag (*)
 if v is unmarked
 mark v
 $parent(v) \leftarrow p$
 for each edge vw (†)
 put (v, w) into the bag (**)



DFS tree



Stack: $O(1)$

h's
 nbers
~~(e, h)~~
~~(e, g)~~
~~(e, f)~~
~~(e, b)~~
~~(e, a)~~
~~(a, e)~~
~~(a, b)~~
~~(phi, a)~~
 Stack:

Just remember: different!

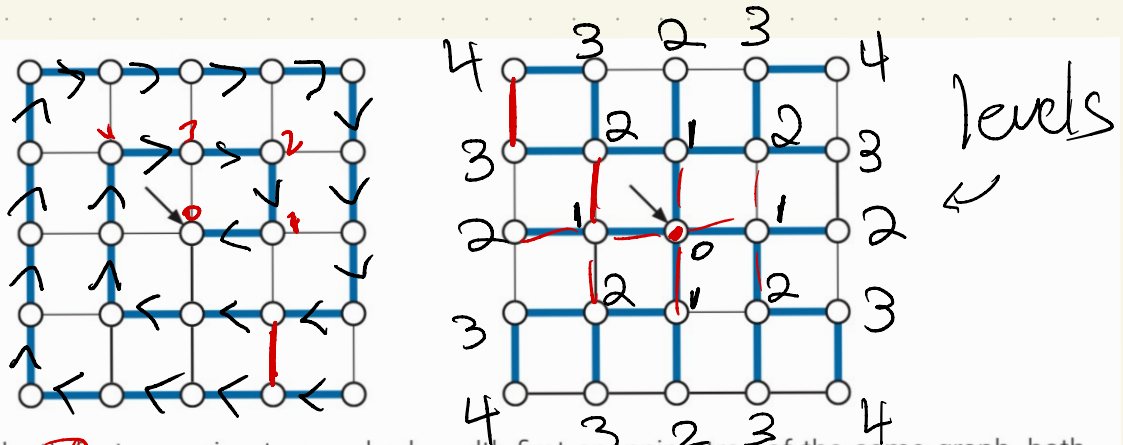


Figure 5.12. A depth-first spanning tree and a breadth-first spanning tree of the same graph, both starting at the center vertex.

DFS:

All non-tree edges must connect a vertex to an ancestor in the tree



BFS:

All non-tree edges must connect vertices either at the same level, or 1 level apart

Runtime:

WHATEVERFIRSTSEARCH(s):

put s into the bag $\leftarrow O(1)$

while the bag is not empty $\leftarrow O(1)$

take v from the bag $\leftarrow O(1)$

if v is unmarked $\leftarrow O(1)$

mark v

for each edge vw

put w into the bag

Think of each edge:
only put on the
stack/queue ≈ 2
time $u \leftrightarrow v$

each edges costs
 $O(1)$ over lifetime of

alg.
If we have connected, $O(V+E)$

Correctness:

Claim: BFS will mark all reachable vertices.

pf: induction on distance to the source:

$d=0$: then vertex = source!
we know this is marked at beginning - see first lines!

$d > 0$: Consider v at distance

d , so $S \rightarrow v_1 \rightarrow v_2 \dots \rightarrow v_{d-1} \rightarrow v$
in G . d edges

assume any vertex at dist $d-1$ is marked

By IH: know v_{d-1} is marked

That means

v_{d-1} was
marked!

WHATEVERFIRSTSEARCH(s):

put s into the bag

while the bag is not empty

take v from the bag

if v is unmarked

mark v

for each edge vw

put w into the bag

started unmarked, so
this line of code ran
with $v = v_{d-1}$

At this point, edge
 $\{v_{d-1}, v_d\}$ is added to bag.

When alg terminates,

v_d will have been popped

← marked.

IMB

Claim: marked v 's + parents
form a spanning tree.

(See demo's...)
← (fast later)

proof :

WHATEVERFIRSTSEARCH(s):

put (\emptyset, s) in bag

while the bag is not empty

take (p, v) from the bag (*)

if v is unmarked

mark v

$parent(v) \leftarrow p$

for each edge vw (†)

put (v, w) into the bag (**)

For each marked vertex:



marked once,
at which point
 (v, p) is added

to tree

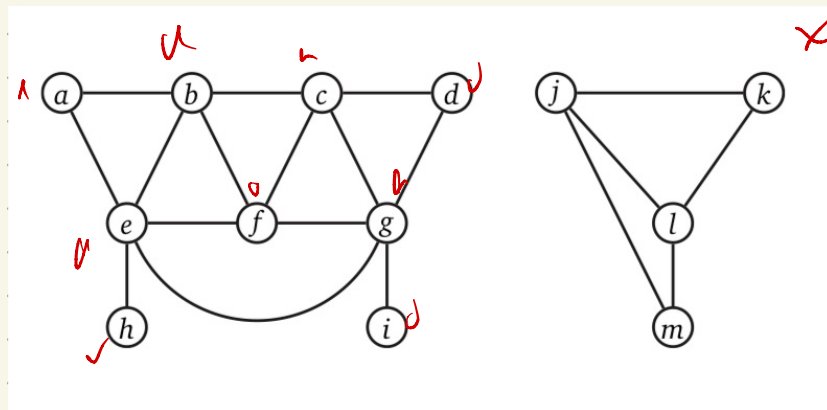
(except s ! because (s, \emptyset) is in tree)

n vertices, $n-1$ edges, connected \Rightarrow tree. \square

In a disconnected graph:

Often want to count or label the components of the graph!

(WFS(v) will only visit the piece that v belongs to.)



Solution: Call it more than one time!
unmark all vertices
For all vertices v :

call WFS(v)
while ~~any~~ any vertex w is unmarked
WFS(w)

Modification: Might want to count the # of connected components:

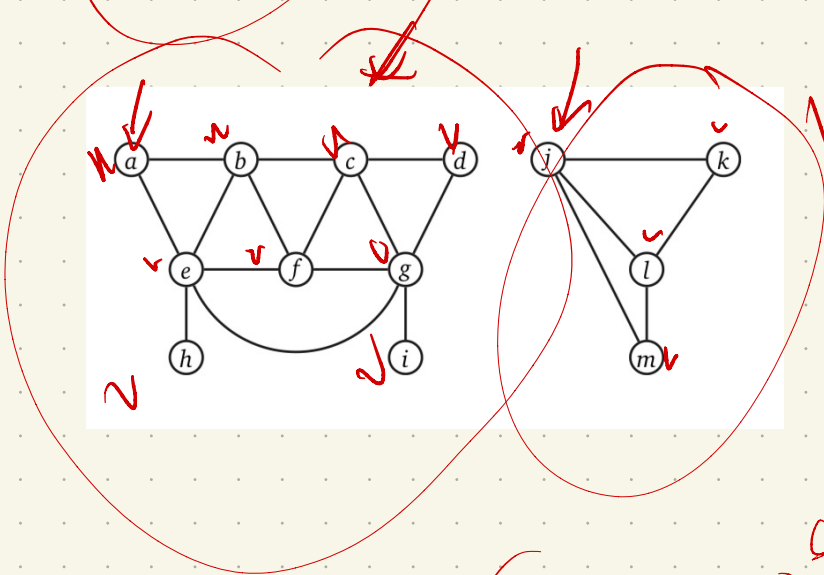
```

COUNTCOMPONENTS(G):
  count ← 0
  for all vertices v
    unmark v
  for all vertices v
    if v is unmarked
      count ← count + 1
      WHATEVERFIRSTSEARCH(v)
  return count
  
```

across alg.
 $O(V+E)$

$V_1 + E_1$

count = 2



$V_2 + E_2$

$= O(c \cdot V + E)$

$\Rightarrow \underbrace{(\# \text{comps}) \cdot V + O(V + E)}$

$\Rightarrow V^2 + E$

Finally, can even record which component each vertex belongs to.

COUNTANDLABEL(G):

```

count ← 0
for all vertices v
  unmark v
for all vertices v
  if v is unmarked
    count ← count + 1
    LABELONE(v, count)
return count
  
```

↑
wts

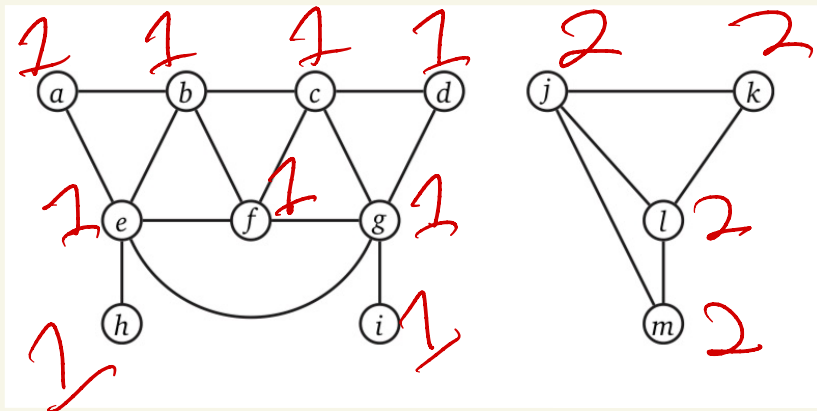
⟨⟨Label one component⟩⟩

LABELONE(v, count):

```

while the bag is not empty
  take v from the bag
  if v is unmarked
    mark v
    comp(v) ← count
    for each edge vw
      put w into the bag
  
```

marked: T/F for each vertex
array
comp[1..V]



$O(1): \text{comp}[u] = \text{comp}[v]?$

Dfn: Reduction

A reduction is a method of solving a problem by transforming it to another problem.

Note: you've seen/done this in other classes!

We'll see a ton of these!

(Especially common in graphs...)

Key: describe how to build a graph

First example:

Given a pixel map, the flood-fill operation lets you select a pixel & change the color of it & all the pixels in its region.

$n \times n$ grid, + value in each cell

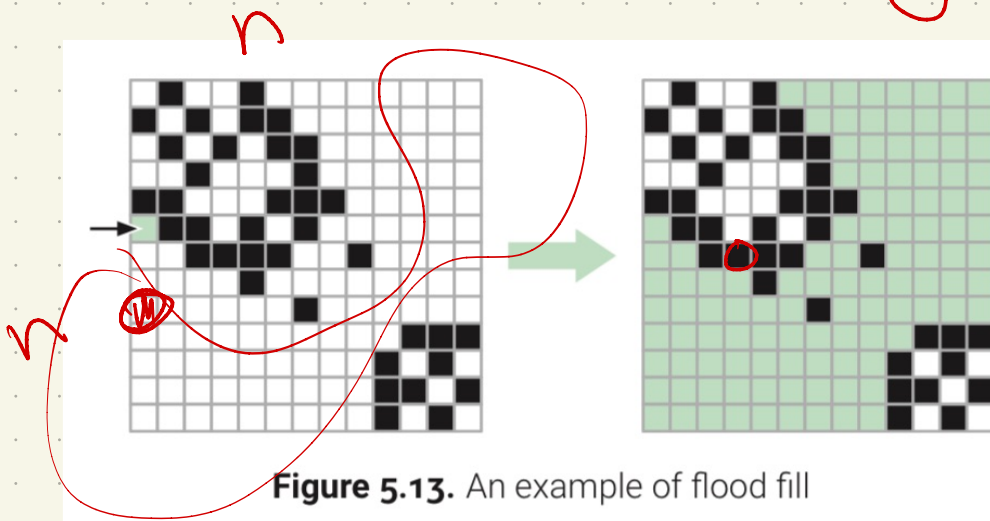


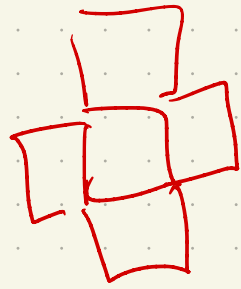
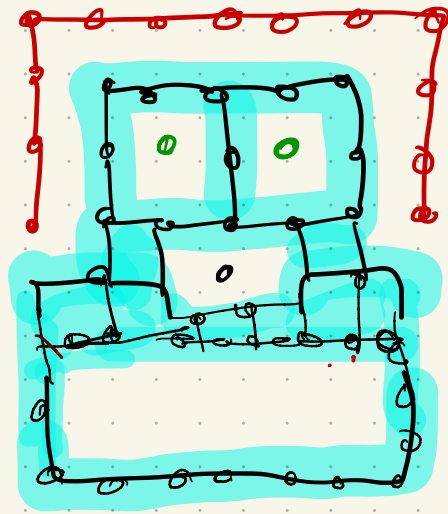
Figure 5.13. An example of flood fill

$P[n][n]$

How?

Convert to a graph problem, & call WFS
BFS or DFS
look at marked vertices

So: Build a graph from pixels:



Build graph: $V = n^2$ Make one vertex per cell.
 $E = 4n^2$ Add 1-4 nbrs as edge

Algorithm

If pixel p is selected:

call WFS (p 's vertex)

reset colour on

any marked vertices

pixels

Runtime: in terms of input!

$\Rightarrow O(n^2)$

Arguably, these reductions
are the most important
thing in graphs!

Like data structures - you
won't usually have to
re-code everything.

Instead:

- Set up graph : $O(n^2)$

- Call some algorithm : $O(n^2)$

$$O(V+E) = O(n^2 + 4n^2) \\ = O(n^2)$$

So runtime/correctness:

Built correct graph
so that alg finds
right object

Next chapter:

All about directed graphs!

First, though, some things to recall: graph traversals.

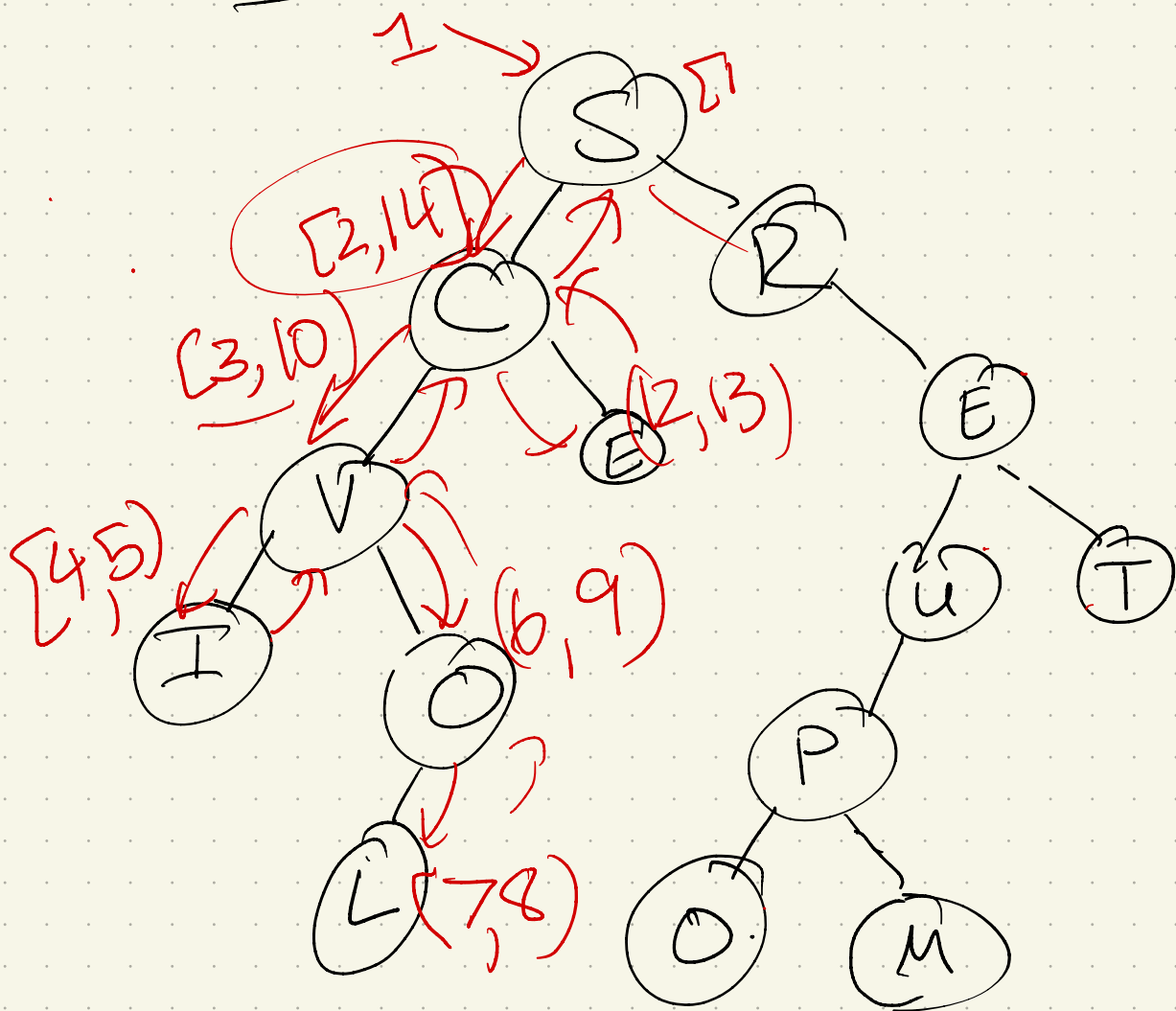
- Pre-order: visit v
visit children

- Post-order: visit all children
visit v

- In-order: (binary tree)

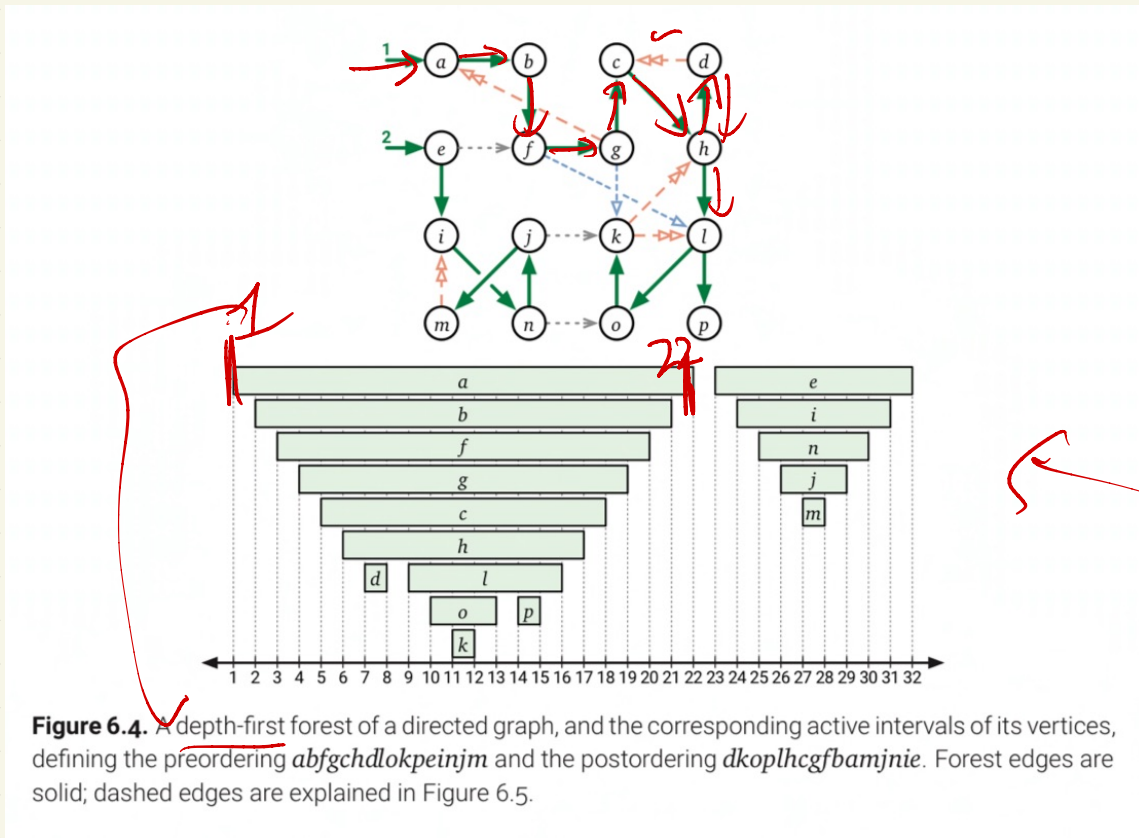
left
self
right

Searching & directed graphs:
Recall : post order traversal



- imagine a "clock" incrementing each time an edge is traversed:

Result:



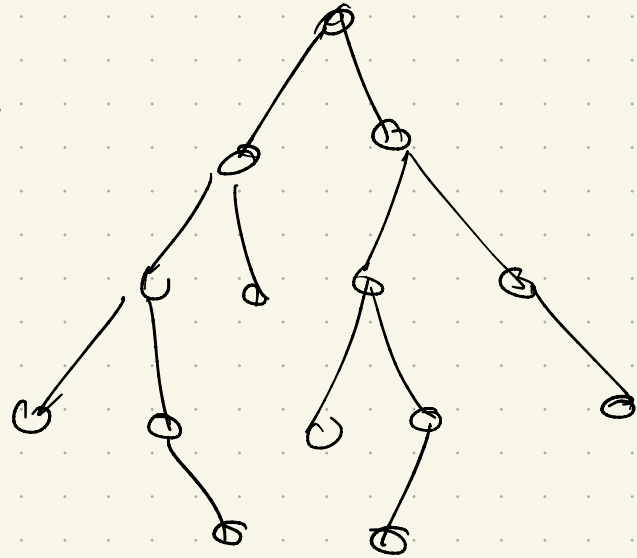
So: in DFS, this "life span" represents how long a vertex is on the stack.

Notation:

$[v_{\text{pre}}, v_{\text{post}}]$

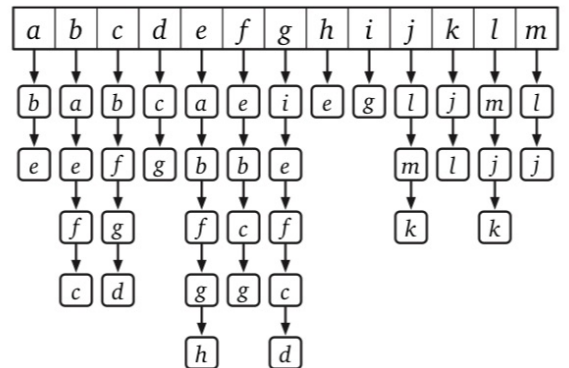
Note: In general graphs,
post order traversal is
not unique!

It was in BSTs:

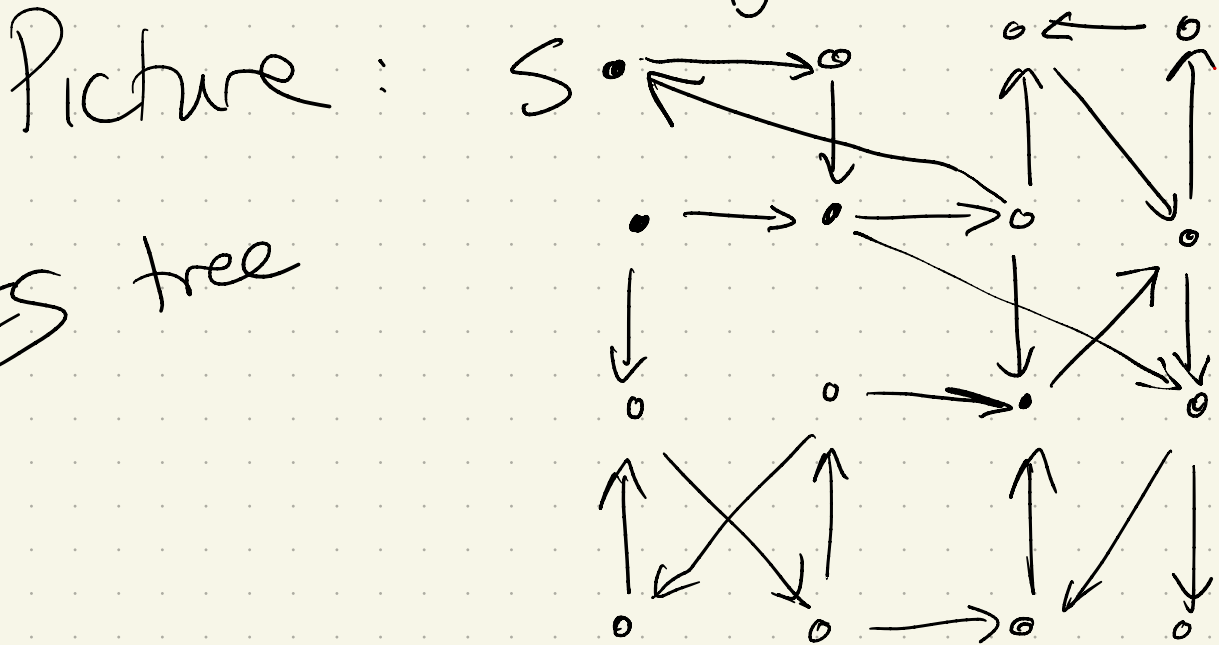


In graphs:
Just use adj. list order.

DFS(v):
if v is unmarked
mark v
for each edge v→w
DFS(w)

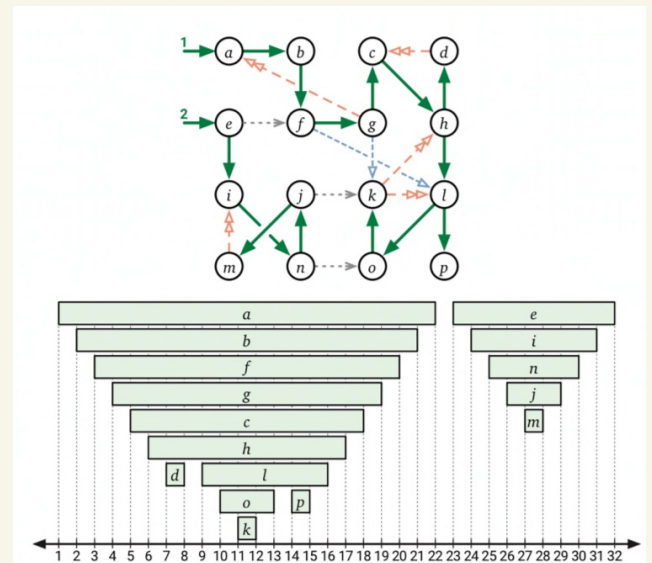


- Dfn:
- tree edge
 - forward edge
 - back edge
 - cross edge



DFS tree

Clock reference:



Finding cycles

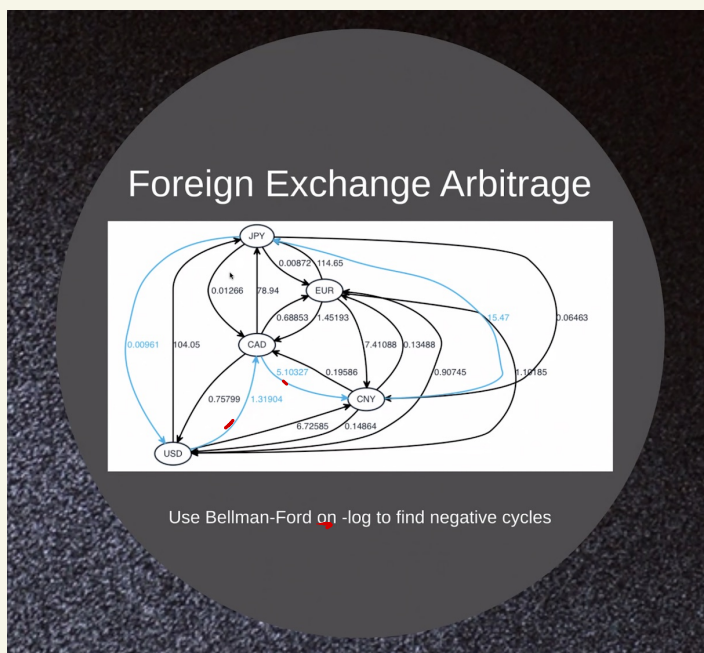
In general, cycles tend to be important.

Sometimes bad:

- topological ordering in a DAG (see next slides)

- longer run time
↳ see Dyn. Pro.

Sometimes good:



(Taken from a talk on high freq. trading)