

CS2100

Sets



Recap

- Work day tomorrow
(on HW & lab)
- Practice Problems sheet
↳ also available
(+ practice final)
- Double check grades in BB
(+ on gtl)
- Still 2 HWs to grade...
- Review Monday
& final next wed. at 2pm

Sets: The set ADT supports several functions:

- $\text{insert}(e)$: insert element e into the data structure
- $\text{find}(e)$: return iterator (or T/F) if e is in set
- $\text{erase}(e)$: remove e from S
- begin/end : return iterator to beginning/ending

Also (in STL):

- $\text{lower_bound}(e)$: return iterator to the largest element $\leq e$
- $\text{upper_bound}(e)$: \parallel
($> e$)
- $\text{equal_range}(e)$: return iterator range of elements $= e$

Issue: can e be in set \Rightarrow tree?

STL:

```
1 // set::lower_bound/upper_bound
2 #include <iostream>
3 #include <set>
4
5 int main ()
6 {
7     std::set<int> myset;
8     std::set<int>::iterator itlow,itup;
9
10    for (int i=1; i<10; i++) myset.insert(i*10); // 10 20 30 40 50 60 70 80 90
11
12    itlow=myset.lower_bound (30);           //           ^
13    itup=myset.upper_bound (60);           //           ^
14
15    myset.erase(itlow,itup);               // 10 20 70 80 90
16
17    std::cout << "myset contains:";
18    for (std::set<int>::iterator it=myset.begin(); it!=myset.end(); ++it)
19        std::cout << ' ' << *it;
20    std::cout << '\n';
21
22    return 0;
23 }
```

Notice that lower_bound(30) returns an iterator to 30, whereas upper_bound(60) returns an iterator to 70. The output of the program is:

```
myset contains: 10 20 70 80 90
```

```
1 // set::count
2 #include <iostream>
3 #include <set>
4
5 int main ()
6 {
7     std::set<int> myset;
8
9     // set some initial values:
10    for (int i=1; i<5; ++i) myset.insert(i*3); // set: 3 6 9 12
11
12    for (int i=0; i<10; ++i)
13    {
14        std::cout << i;
15        if (myset.count(i)!=0)
16            std::cout << " is an element of myset.\n";
17        else
18            std::cout << " is not an element of myset.\n";
19    }
20
21    return 0;
22 }
```

Output:

```
0 is not an element of myset.
1 is not an element of myset.
2 is not an element of myset.
3 is an element of myset.
4 is not an element of myset.
5 is not an element of myset.
6 is an element of myset.
7 is not an element of myset.
8 is not an element of myset.
9 is an element of myset.
```

How to implement?

- List - probably sorted
 - ↳ private:

List<T> mydata;

// functions can use
list helper functions

- Vector
(same)

- AVL tree

STL: balanced BST
↳ red-black tree

Trade-offs:

Space: $O(n)$

Functions:

(balanced Search) Tree :
all $O(\log n)$

Vector :

insert: $O(n)$

↳ search $O(\log n)$
↳ insert in Vec $O(n)$

find: $O(\log n)$

List :

insert : $O(n)$
(if sorted)

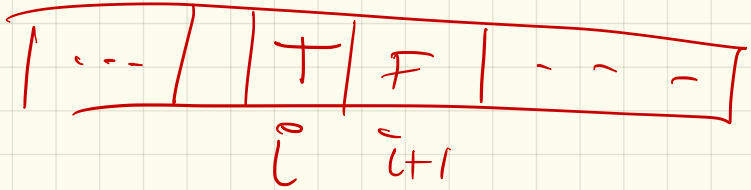
find: $O(n)$

One other option:

Bit Vector

pool values [max value];

If values ^{in set} range from
0 to $N-1$



Downside: space!

With n values,

size is still $O(N)$.

Lookup, insert & remove:

$O(1)$

Mergable Sets:

Adds:

- union (S_1, S_2): returns a new set containing all elements in S_1 or S_2



Note: Could also merge the two objects

- interset (S_1, S_2):



- setminus (S_1, S_2):



Runtime

depends!

vector or List: $O(n)$

Special case: Union-find

Only 3 operations

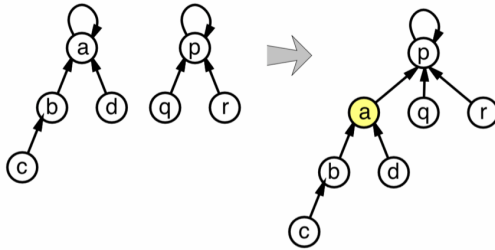
- `makeSet(x)`: create a set containing only x
- `union(A, B)`: return $A \cup B$
(+ destroy A + B)
- `find(p)`: return the set containing p .

Implementation:

MAKESET(x):
 $\text{parent}(x) \leftarrow x$

FIND(x):
while $x \neq \text{parent}(x)$
 $x \leftarrow \text{parent}(x)$
return x

UNION(x, y):
 $\bar{x} \leftarrow \text{FIND}(x)$
 $\bar{y} \leftarrow \text{FIND}(y)$
 $\text{parent}(\bar{y}) \leftarrow \bar{x}$



- Each set needs to "know" its component
- Initially, each set is its own \rightarrow n labels
- When combining 2,
 - take smaller set & relabel all of its vertices(See prev. slide)

• Then, each time a component label changes, its set is \geq twice as large.

So: each label can change only $O(\log n)$ times.

(used for MST algorithm)