

CS 2100

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Graphs - pt 1

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# Recap

- Lab 10 - extended until tonight
- HW 9 - next Wed.
- no class Thurs, Fri, & Mon.
- HW 10 over graphs
  - ↳ up next week, due last Fri. of classes
- Review session on final day
- Final exam: Wed. of finals at 2pm
  - Conflicts or accommodations, let me know ASAP!

# Graphs

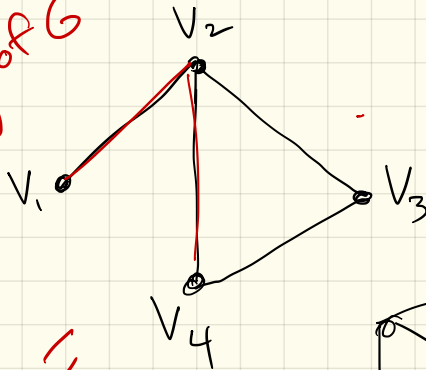
A graph  $G = (V, E)$  is an ordered pair of 2 sets:

$$V = \text{vertices} = \{v_1, v_2, v_3, v_4\}$$

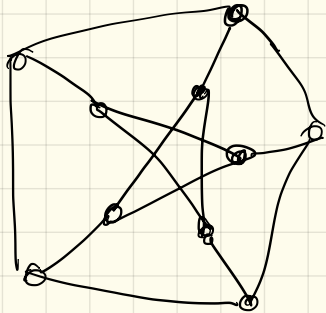
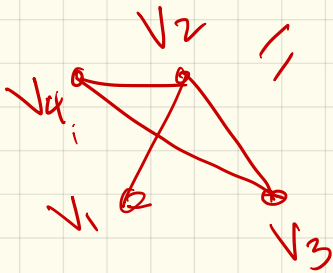
$$E = \text{edges} = \{\{v_1, v_2\}, \{v_2, v_4\}, \dots\}$$

View:

Drawing of  $G$



||  
↓



Why?

They model everything!

Examples

↑  
non-hierarchical,  
non-linear

→ road networks  
social connection  
internet

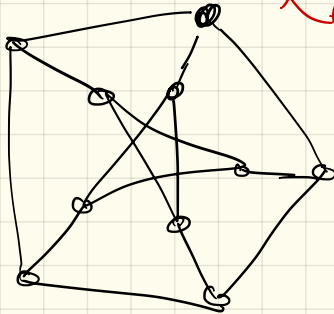
o  
o  
o

More defs:

$G$  is undirected if edges are unordered pairs

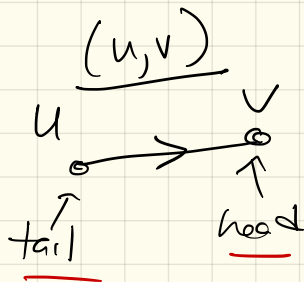
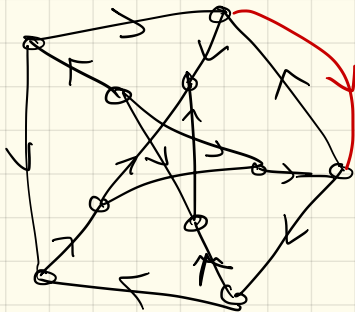
$$\text{so } \{u, v\} = \{v, u\}$$

endpts



$G$  is directed if edges are ordered pairs

$$\text{so } (u, v) \neq (v, u)$$



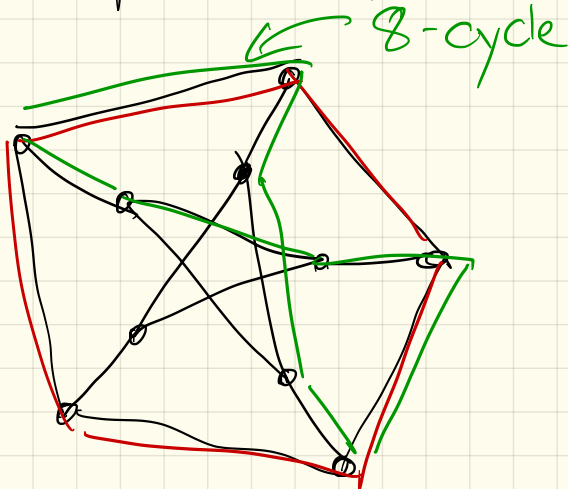
Dfns cont :

The degree of a vertex,  $d(v)$ , is the number of adjacent edges.

A path  $P = v_1, \dots, v_k$  is a set of vertices with  $\{v_i, v_{i+1}\} \in E$   
(or  $(v_i, v_{i+1}) \in E$  if directed)

A path is simple if all vertices are distinct

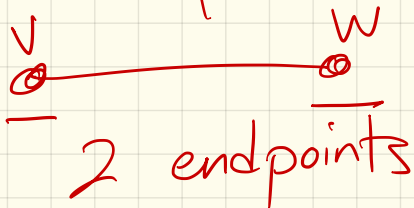
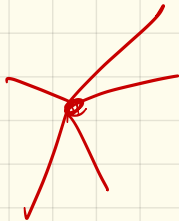
A cycle is a path which is simple except  $v_1 = v_k$ .



Lemma: (degree-sum formula)

$$\sum_{v \in V} d(v) = 2|E|$$

pf:



every edge adds +1  
so  $\sum$  on left  
exactly twice.

Size of G:

2 parameters:

$$|V| = \underline{n}$$

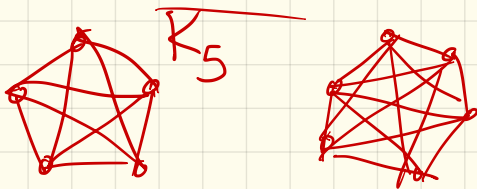
$$|E| = \underline{m}$$

How big can  $m$  be in terms of  $n$ ?

For every 2 vertices could have 1 edge.

$$\binom{n}{2} = \frac{n(n-1)}{2} = O(n^2)$$

Worst case:  $K_n$

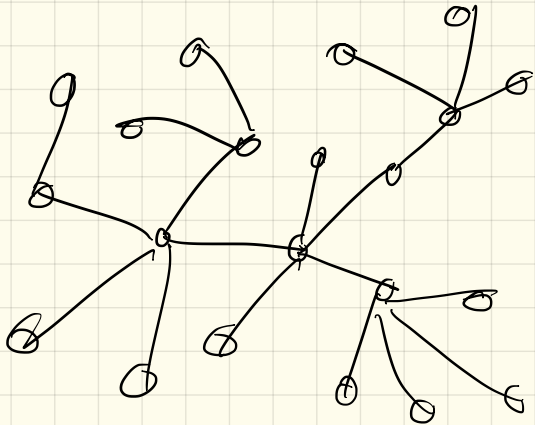
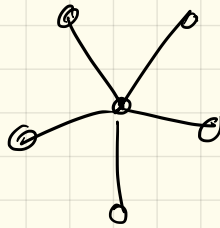
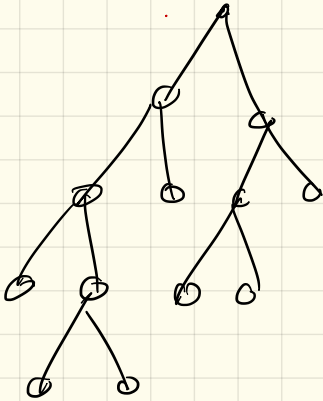




# Tree :

A connected graph with  
no cycles

(Note: no root here!)



# Representing graphs

How do we make this data structure?

Build it from ones we've seen already.

# Adjacency (or vertex) lists:

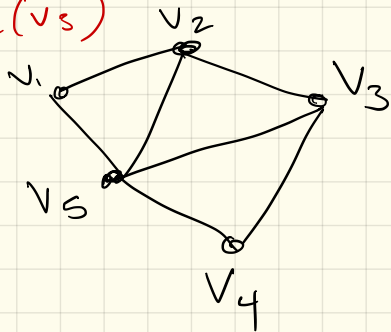
$V_1 \circledast V_2, V_5$

$V_2 \circledast V_1, V_3 \leftarrow d(V_2)$

$V_3 \circledast V_2, V_4, V_5 \leftarrow d(V_3)$

$V_4 \circledast \dots$

$V_5 \circledast \dots$



in terms of  $n$  &  $m$   
1 per vertex  
(list)

Size :  $n + 2m = O(m+n)$

Lookup : Time to check if  $V_i + V_j$   
are hrs :

$O(n) \rightarrow d(V_i)$  or  $d(V_j)$   
but - tricky! list or vector.

## Implementation:

We call these vertex lists,  
but don't have to  
use lists

## Options:

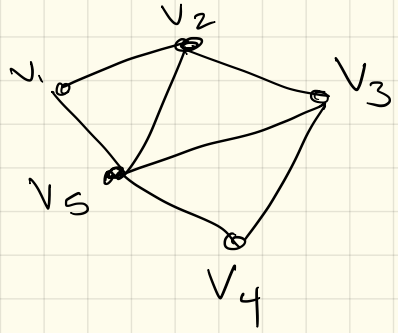
- vector
- list
- BST (?)

## Trade-offs:

Binary search  
 $O(1)$  - insertion

# Adjacency Matrix

	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$
$v_1$	X	1	0	0	1
$v_2$	X	X	1	0	1
$v_3$		X	X	1	1
$v_4$			X	X	1
$v_5$					X



Space:  $O(n^2)$   
check nbr:  $O(i)$   
 $A[i][j] == 1?$

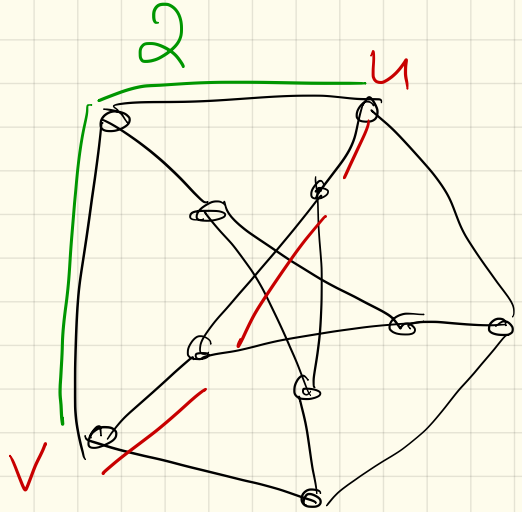
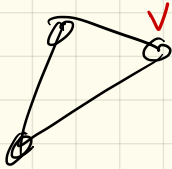
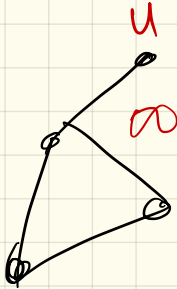
Which is better?

Depends!

	Adjacency matrix	Standard adjacency list (linked lists)	Adjacency list (hash tables)
Space	$\Theta(V^2)$	$\Theta(V + E)$	$\Theta(V + E)$
Time to test if $uv \in E$	$O(1)$	$O(1 + \min\{\deg(u), \deg(v)\}) = O(V)$	$O(1)$
Time to test if $u \rightarrow v \in E$	$O(1)$	$O(1 + \deg(u)) = O(V)$	$O(1)$
Time to list the neighbors of $v$	$O(V)$	$O(1 + \deg(v))$	$O(1 + \deg(v))$
Time to list all edges	$\Theta(V^2)$	$\Theta(V + E)$	$\Theta(V + E)$
Time to add edge $uv$	$O(1)$	$O(1)$	$O(1)^*$
Time to delete edge $uv$	$O(1)$	$O(\deg(u) + \deg(v)) = O(V)$	$O(1)^*$

Dfn:

- $G$  is connected if  $\forall u, v$ , there  $\exists$  path from  $u$  to  $v$ .
- The distance from  $u$  to  $v$ ,  $d(u, v)$ , is equal to the # of edges on the minimum  $u, v$ -path



# Algorithms on graphs

Basic 1<sup>st</sup> question:

Given any 2 vertices, are they connected?

Also: what is their distance?  
↳ minimum path

How to solve?



Suggestion:

Suppose we're in a maze,  
Searching for something.  
What do you do?

right hand rule -  
Search until  
reach previously  
seen room

↳ depth first search

# Pseudocode : two versions

## RECURSIVEDFS(v):

if  $v$  is unmarked

mark  $v$

for each edge  $vw$

RECURSIVEDFS( $w$ )

## ITERATIVEDFS(s):

PUSH( $s$ )

while the stack is not empty

$v \leftarrow$  POP

if  $v$  is unmarked

mark  $v$

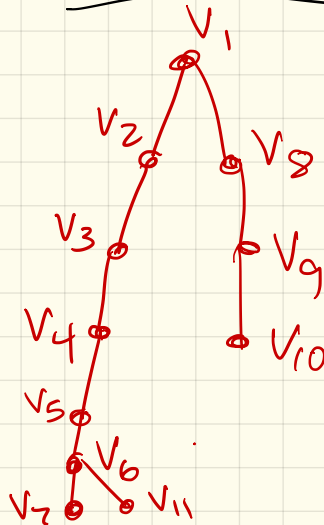
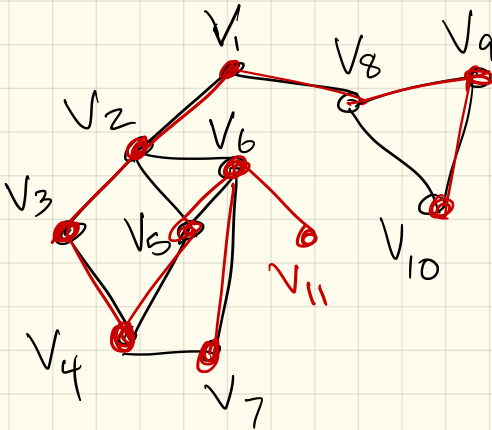
for each edge  $vw$

PUSH( $w$ )

↑ runtime!

Really, building a "tree" :

DFS tree:



# General traversal strategy's

TRAVERSE(s):

```
put s into the bag
while the bag is not empty
  take v from the bag
  if v is unmarked
    mark v
    for each edge vw
      put w into the bag
```

Q: Can we use a different "bag"?

BFS: use a queue

TRAVERSE(s):

put  $s$  into the bag

while the bag is not empty

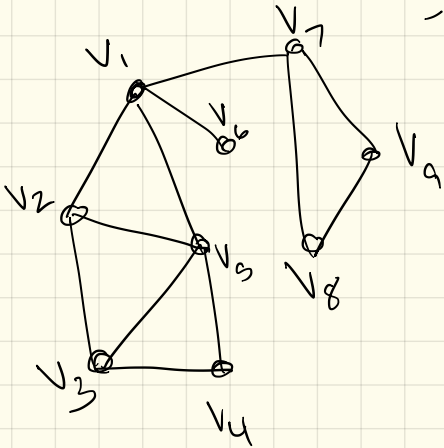
take  $v$  from the bag

if  $v$  is unmarked

mark  $v$

for each edge  $vw$

put  $w$  into the bag



BFS vs. DFS: