

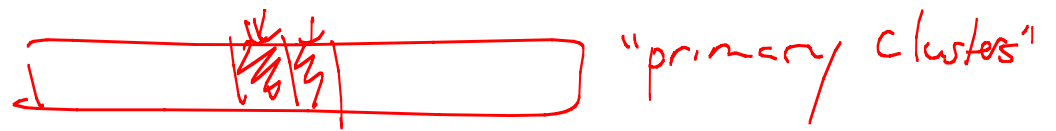
# CS180 - Treaps

Note Title

5/4/2011

## Announcements

- Program due tomorrow
- HW due next Monday
- Review next Friday at 10:30  
(check webpage/ Thursday, in case of a room change)
- Final Monday at noon
- No conflict (so far)



## Final comments on Hashing (recap)

- ① convert key to 32-bit int,  $k$
- ② Compute  $h(k)$ , a value between  $0 \rightarrow N-1$

Goals:

- fast -  $O(1)$
- minimize collisions

③ Deal with collisions. How?

- auxiliary data structure (list, tree, etc.)
- linear probing
- quadratic probing

## Issues with Quadratic Probing:

- Can still cause "secondary" clustering
- N really must be prime for this to work
- Even with  $N$  prime, starts to fail when array gets half full

(Runtimes are essentially the same)

Even worse: this can just fail: the array has an empty spot, but this function can't get to it

## Secondary Hashing

- Try  $A[h(k)]$

- If full, try  $A[h(k) + f(j) \bmod N]$   
for  $j = 1, 2, 3, \dots$

where

$$f(j) = j \cdot h'(k)$$

another  
hash fun



quadratic, we had  
 $f(j) = j^2$

with  $h'$  a different  
hash function

## Load Factors

Separate chaining actually works as well as most others in practice, although it does use more space.

Most of these methods only work well if  $\frac{n}{N} < 0.5$ .

(Even chaining starts to fail if  $\frac{n}{N} > 0.9$ )

## Rehashing

Because we need  $\frac{n}{N} < 0.5$ , most hash code checks if the array has become more than half full.

If so, it stops & recomputes everything for a larger  $N$ , usually at least twice as big.

(Still not too bad in an amortized sense - think vectors.)

## In practice

Hashing is the fastest thing!

Given a good load factor, this uses a small amount of space and runs in  $O(1)$  time.

This is a good example when the guaranteed run times are very different from what we see in practice.

Treaps: a new binary tree data structure

Tree + heap

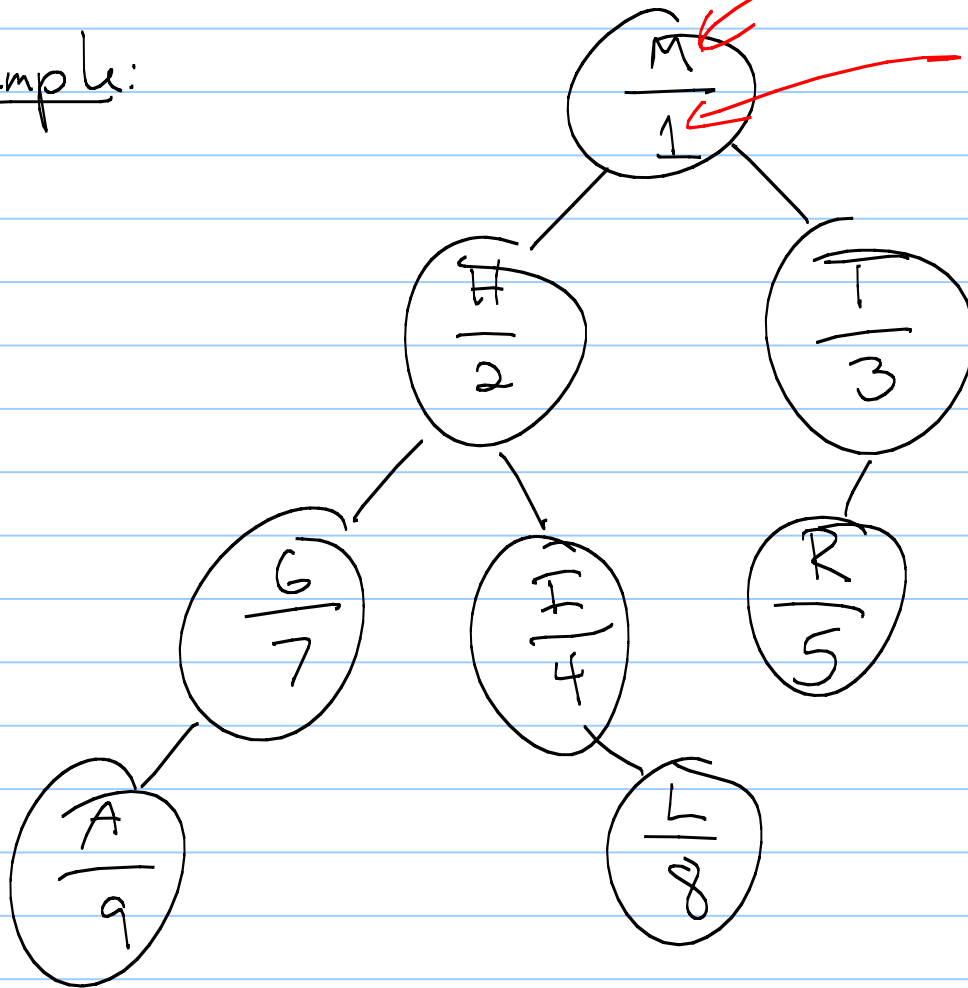
- Nodes will contain both values and priorities
- A treap is a BST over the values and a heap over the priorities.

Use letters → int  
↑ ↑  
values priorities

min heap



Example:



letters form a BST

numbers give a min heap

(letters are in alpha. order)

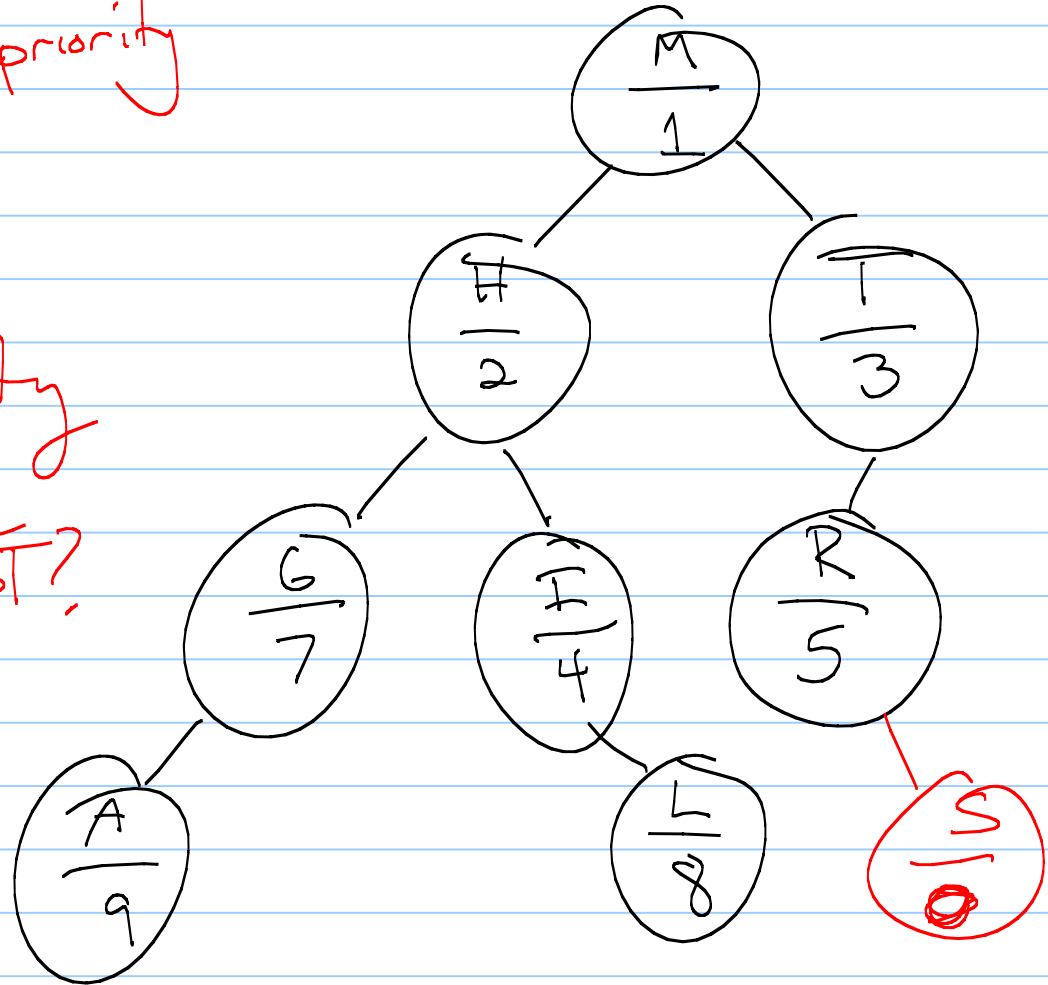
# Insert

insert:  $(S, 0)$

*data* (pointing to S)  
*priority* (pointing to 0)

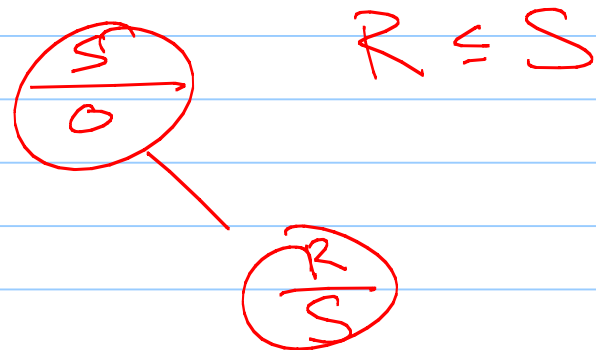
forget priority  
where should  
S go in BST?

Am I a  
min heap?



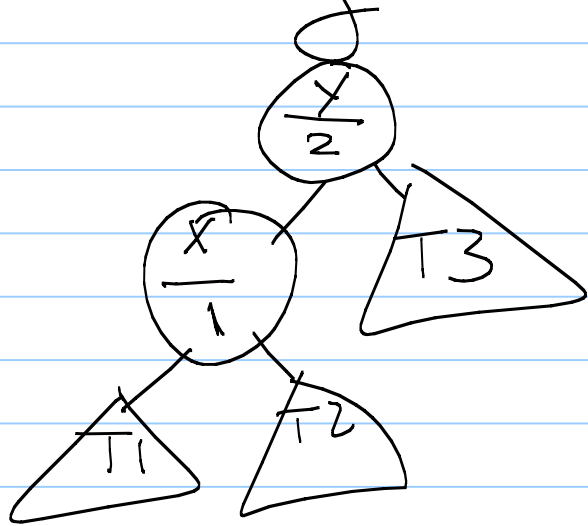
In heap, we "bubble up".  
Will that work here?

No. If I swap of R & S nodes no longer a BST over values.



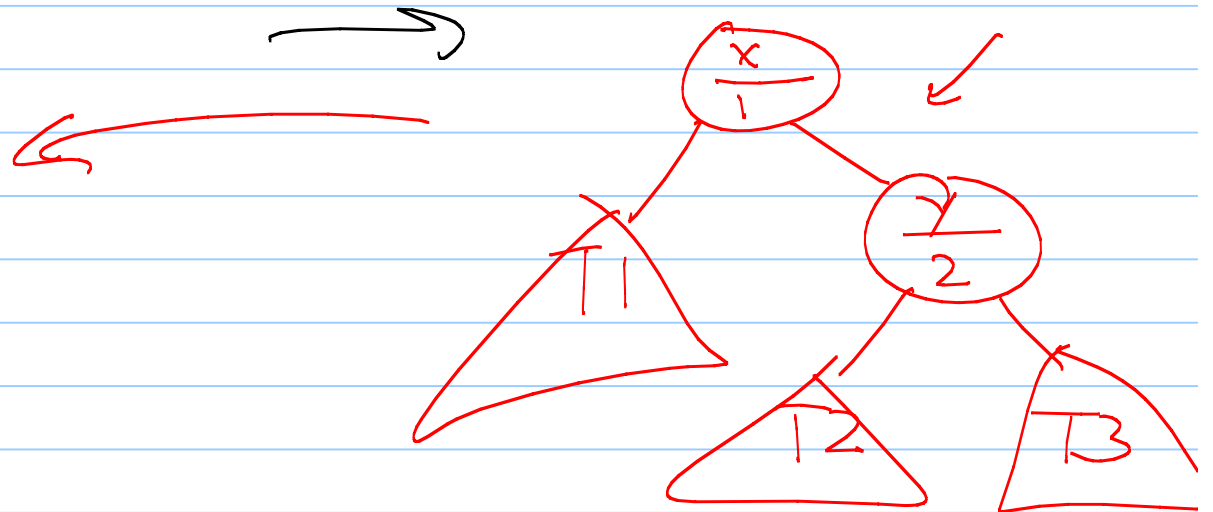
# Rotations

$x$  &  $y$  are in correct BST order, with  $x \leq y$ , but priorities are wrong

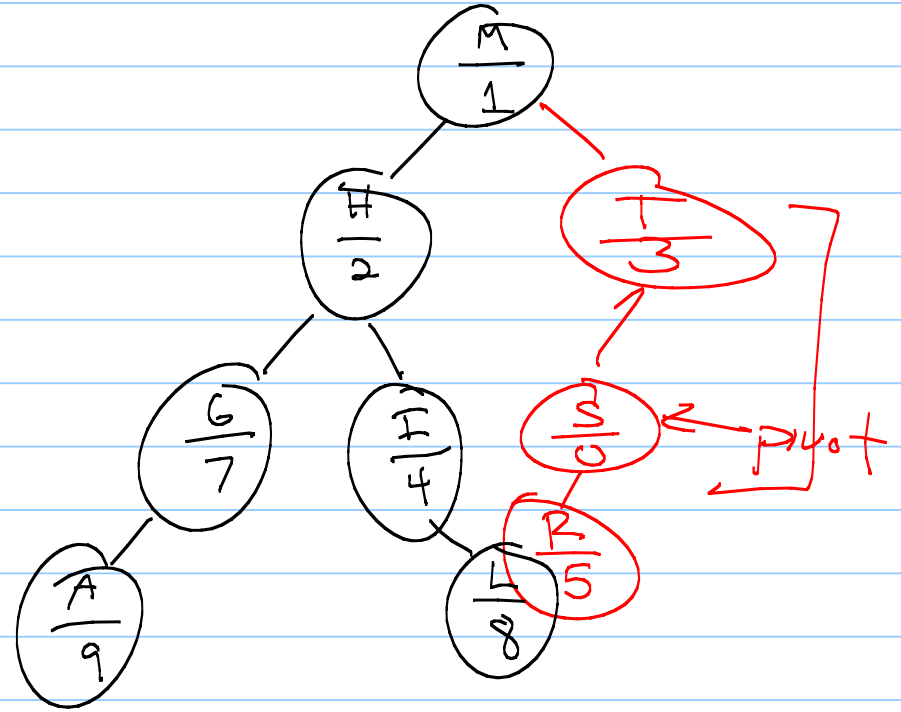
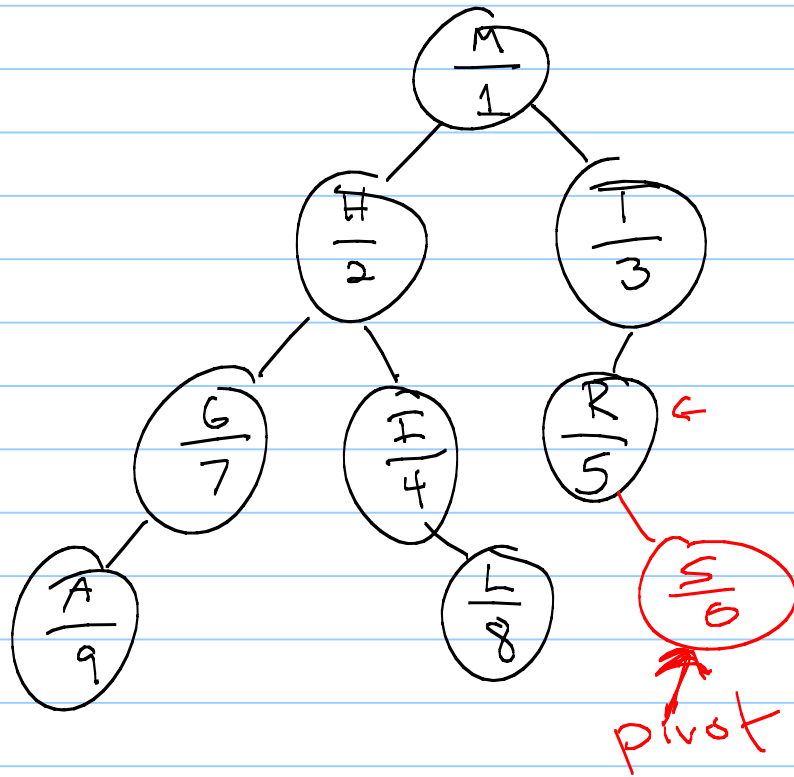


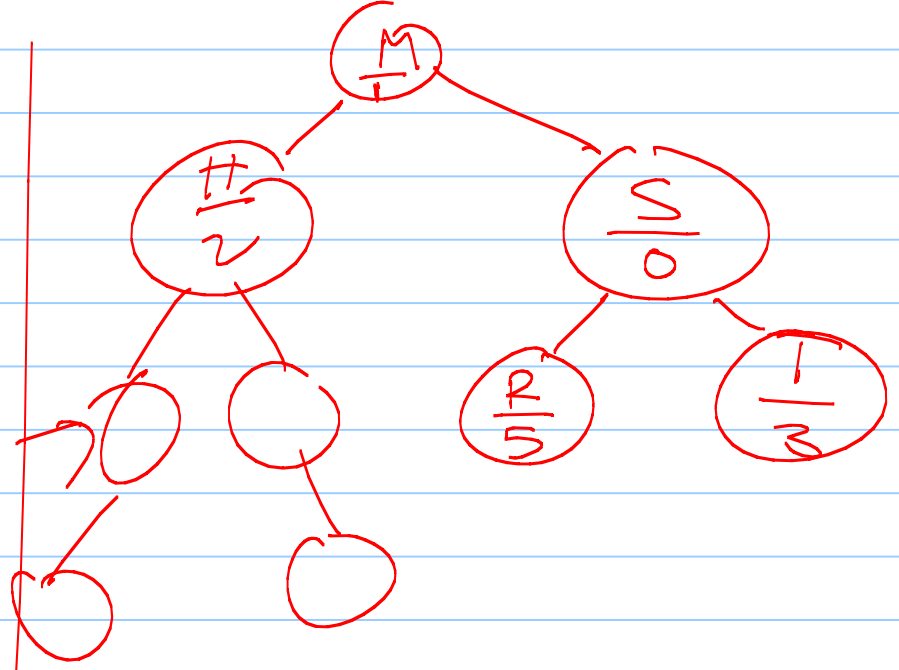
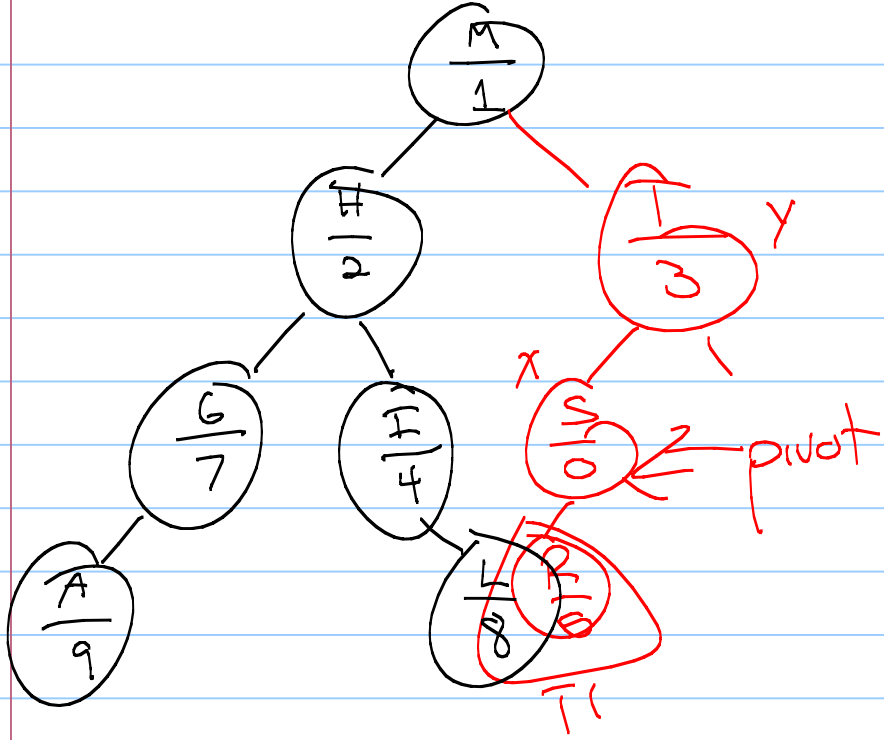
Fix:

Nice: this is just our pivot.

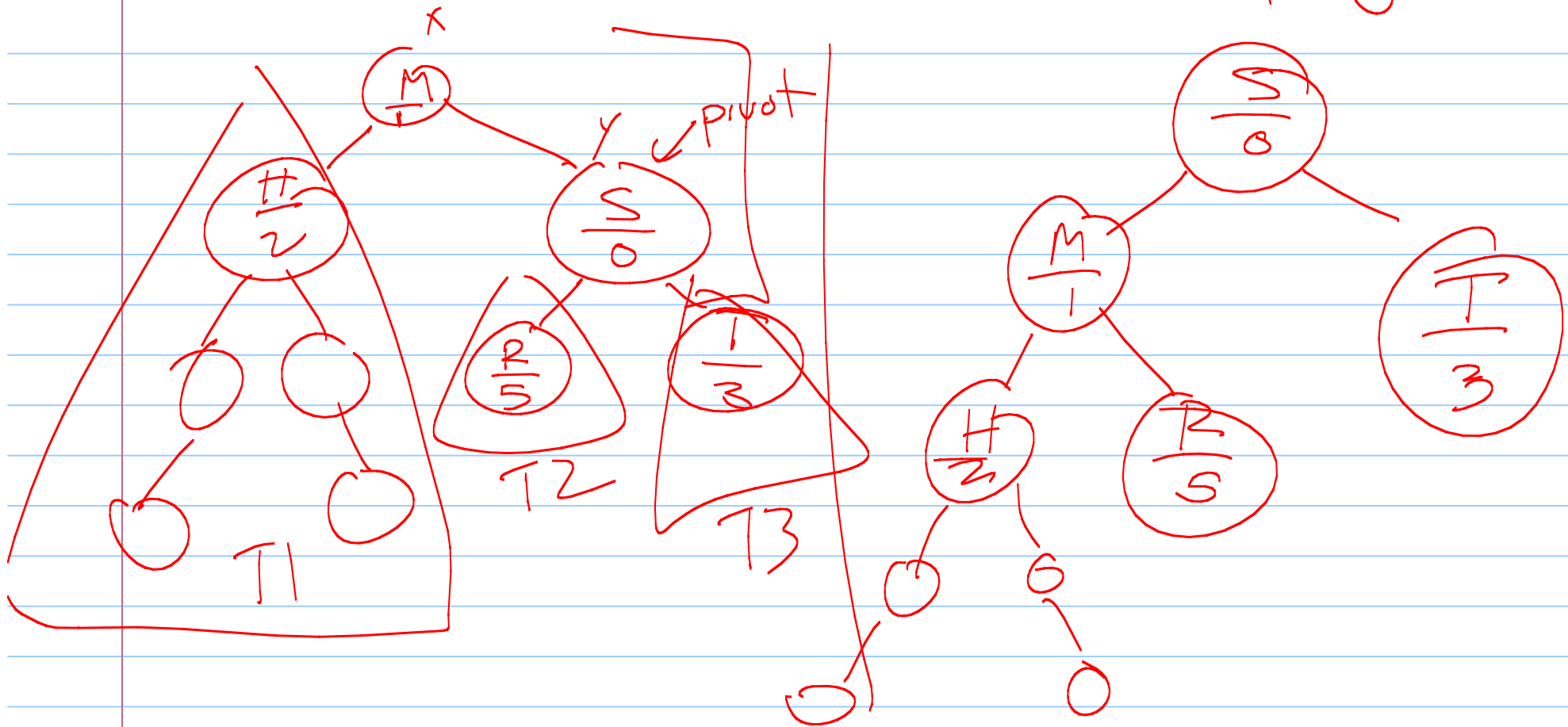


So: insert (S, 0)





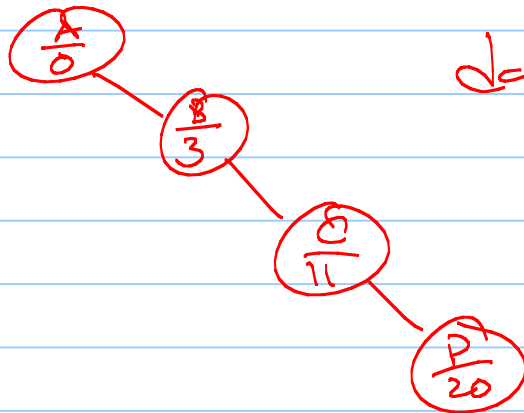
Treap again!



Downside: What can height be?

Can we force them to be balanced?

No:  $(A, 0)$   $(B, 3)$   $(C, 11)$   $(D, 20)$

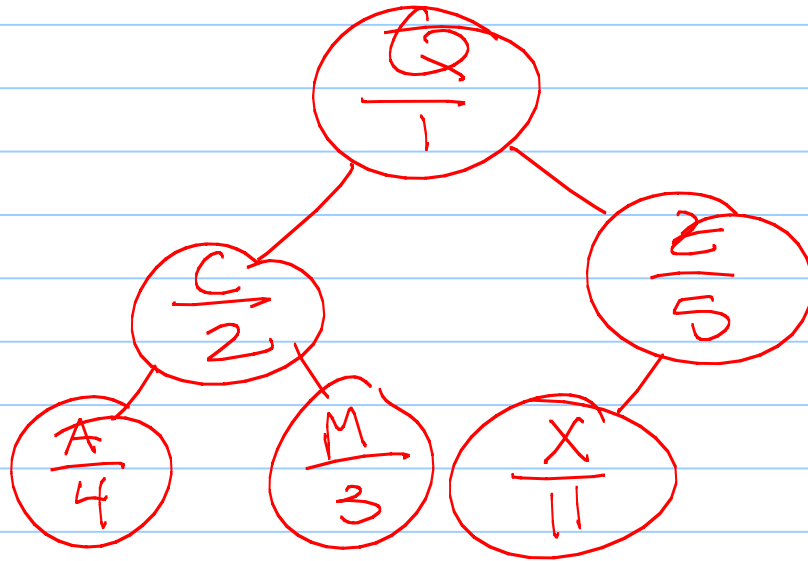


Each set of data has a unique freq.



Draw heap with  ~~$(A, 4)$~~ ,  ~~$(C, 2)$~~   
 ~~$(X, 11)$~~ ,  ~~$(M, 3)$~~ ,  ~~$(Q, 1)$~~ ,  ~~$(Z, 5)$~~   
Who is root?

(save tons  
of time)



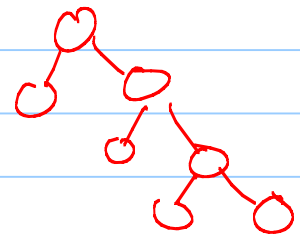
## Randomized treaps :

Alternative to AVL trees.

Each element will get a random priority.

Expected height of the treap will be  $O(\log n)$ .

Worst case is still  $O(n)$ .



Code: How do we implement?

Inherit from Binary Search Tree.

→ priorities are in `_aux`.

→ insert (use pivot to fix)

→ delete

(look for extra lecture notes)